

Performance Analysis and Design of Tandem Queues with Blocking

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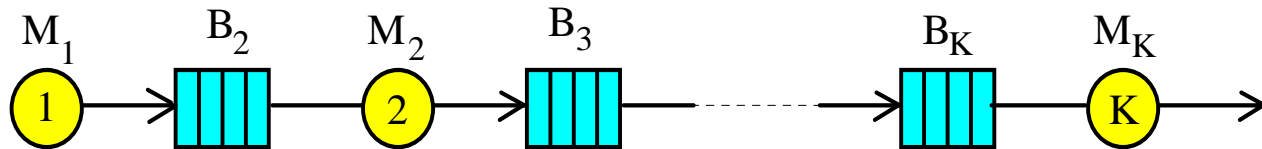
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Analysis of Tandem Systems (Queues in Series with Finite Buffers)



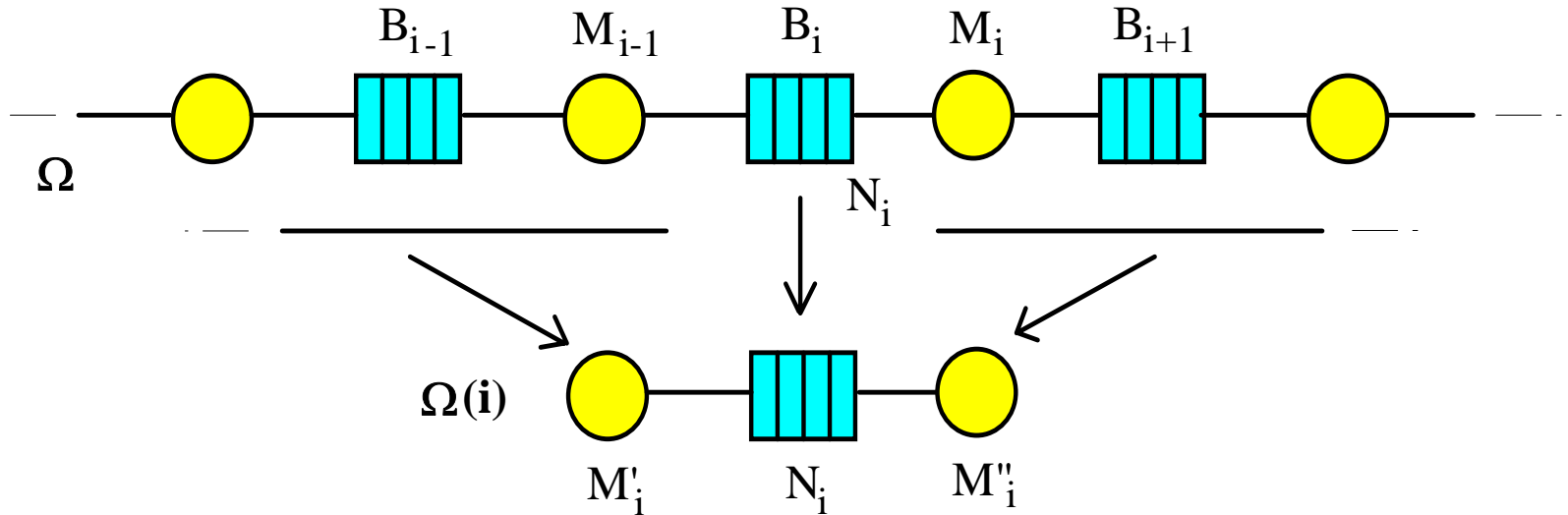
- Random processing times
- Finite-capacity buffers
- Blocking
- Starvation

$X_i =$ processing time at M_i

$\{N_1(t), J_1(t); N_2(t), J_2(t); \dots; N_K(t), J_K(t), t \geq 0\}$

<u>Metrics of Interest:</u>	$\left\{ \begin{array}{l} \text{Throughput: } \bar{o}_i \\ \text{Avg. WIP: } \bar{N}_i \end{array} \right.$	$P_i(0), P_i(B)$

Concept of Disaggregation



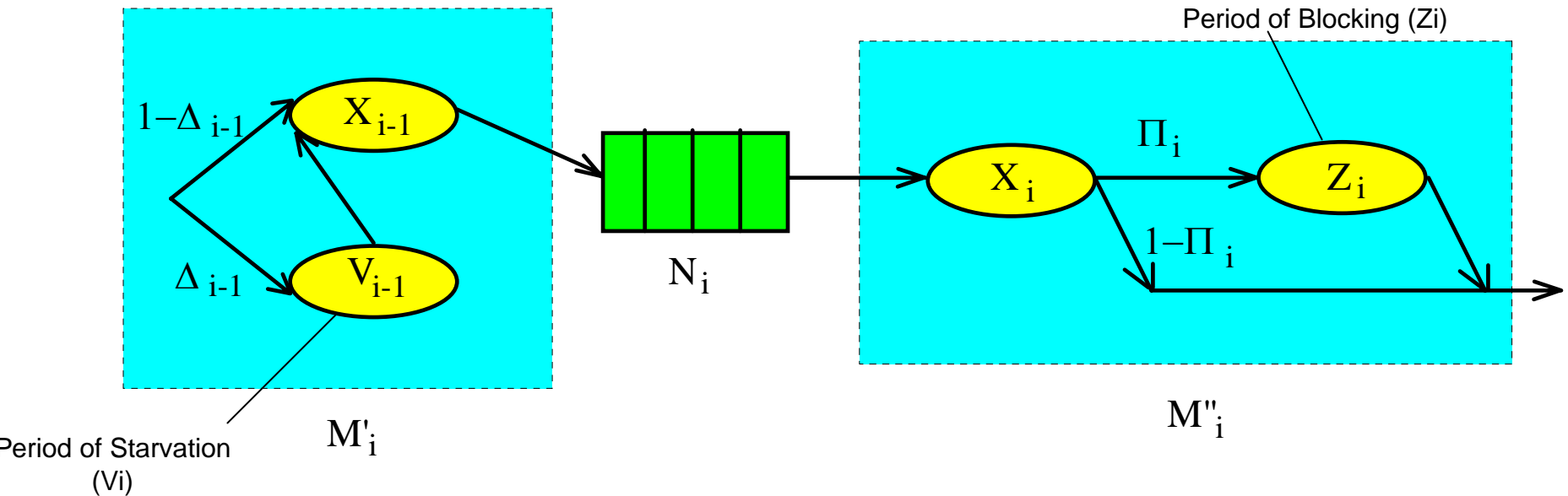
$\Delta_i = \Pr(\text{a departing job leaves } M_i \text{ empty and idle})$

$V_i = \text{Length of the idle period at } M_i$

$\Pi_i = \Pr(\text{a departing job blocks } M_i)$

$Z_i = \text{Length of period } M_i \text{ remains blocked}$

Isolation of Buffers



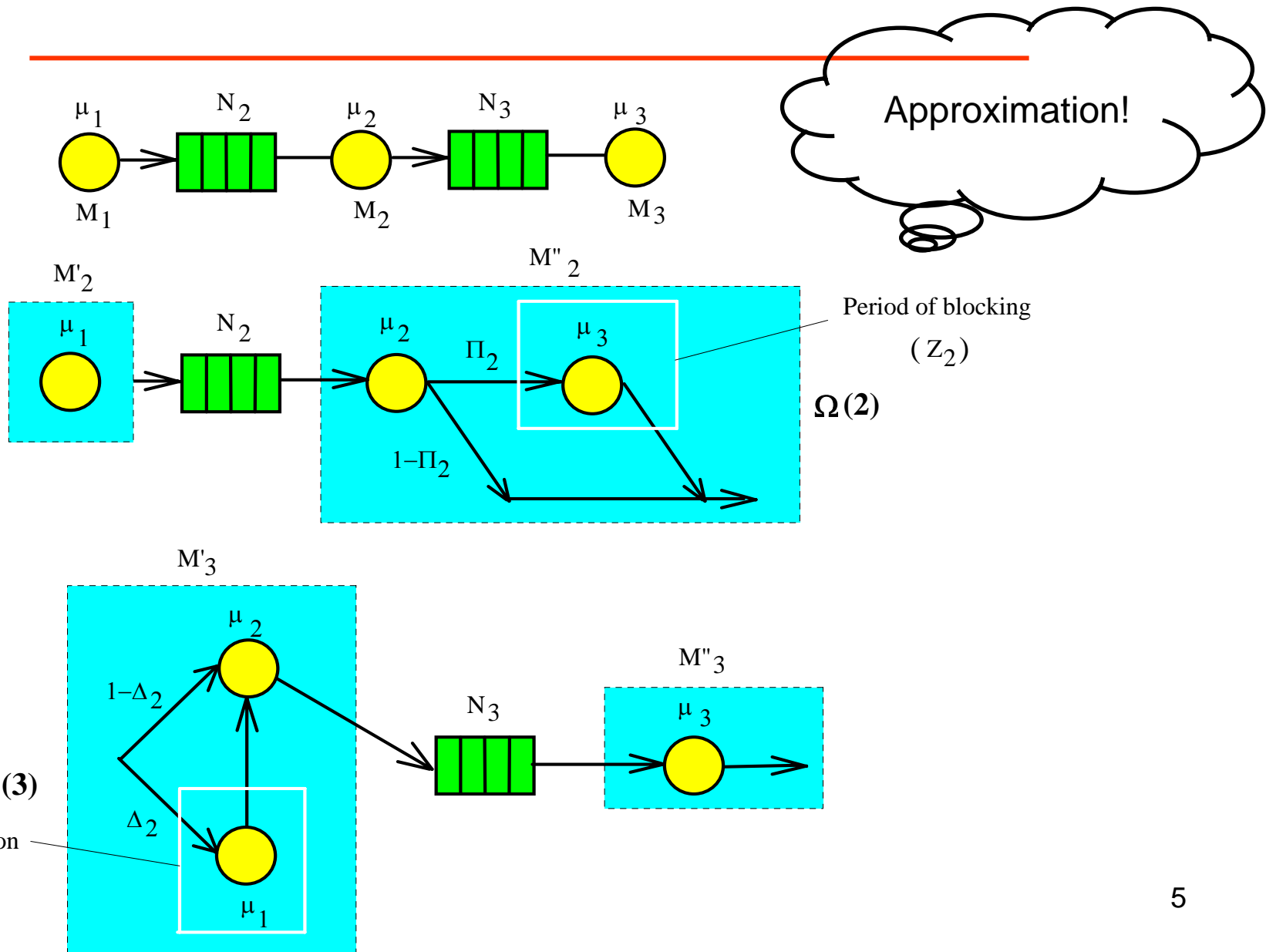
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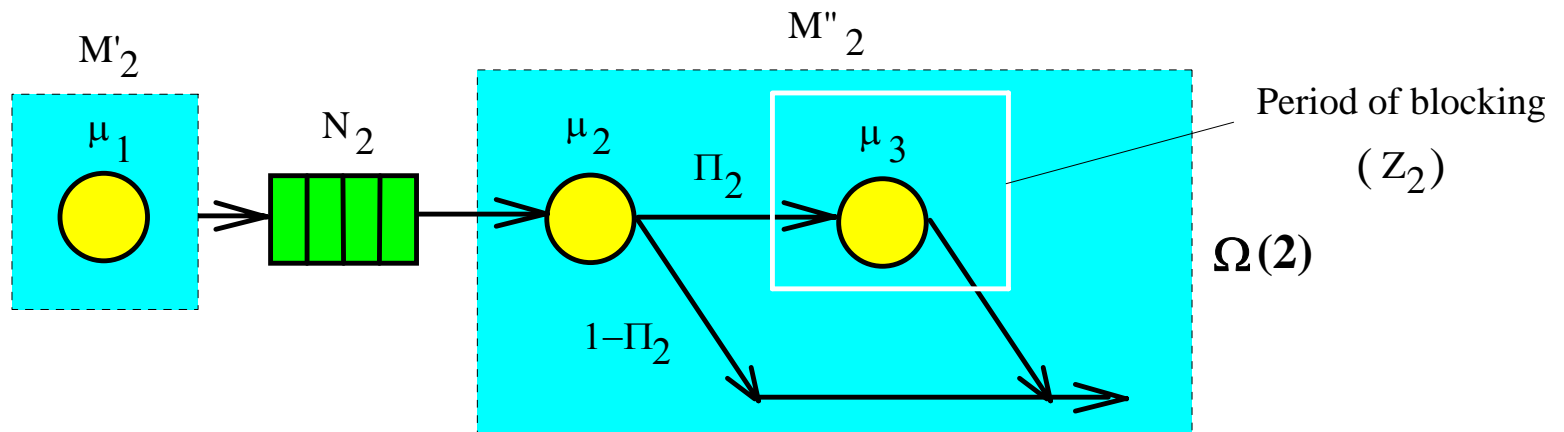
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Two Nodes Decomposition: An Example



$\Omega(2)$



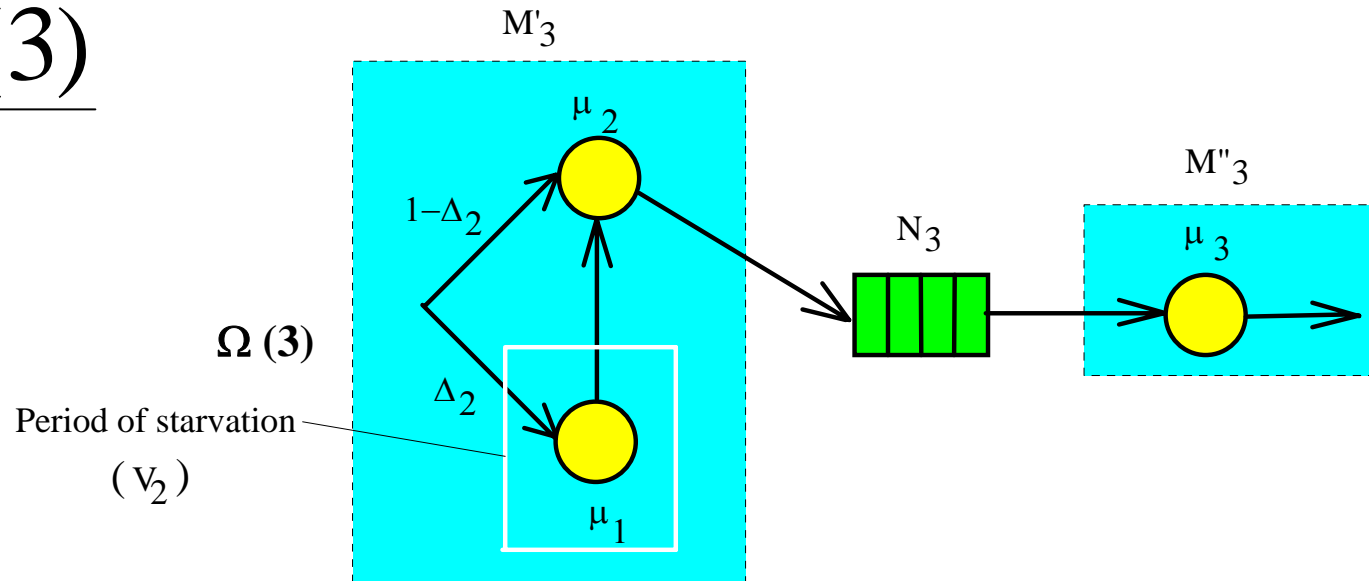
$\{N_2(t), J_2(t), t \geq 0\}$ is a continuous-time MC.

SS probabilities can be solved for using matrix-recursive methods.

$$P_2(n, j), n = 0, 1, 2, \dots, N_2, B, \quad j = 0, 1, 2$$

$$P_2(n) = \sum_j P_2(n, j)$$

$\Omega(3)$



$\{J_2(t), N_3(t), t \geq 0\}$ is a continuous-time MC.

$$P_3(j, n), \quad j = 0, 1, 2, \quad n = 0, 1, 2, \dots, N_3, B$$

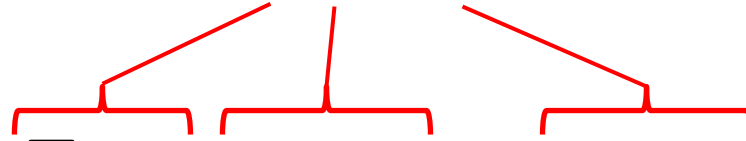
$$P_3(n) = \sum_j P_3(j, n)$$

Linking $\Omega(2)$ & $\Omega(3)$

- Need to compute Δ_2 and Π_2

Using Little's formula:

$$\boxed{??} = \boxed{??}$$



$\Omega(3)$

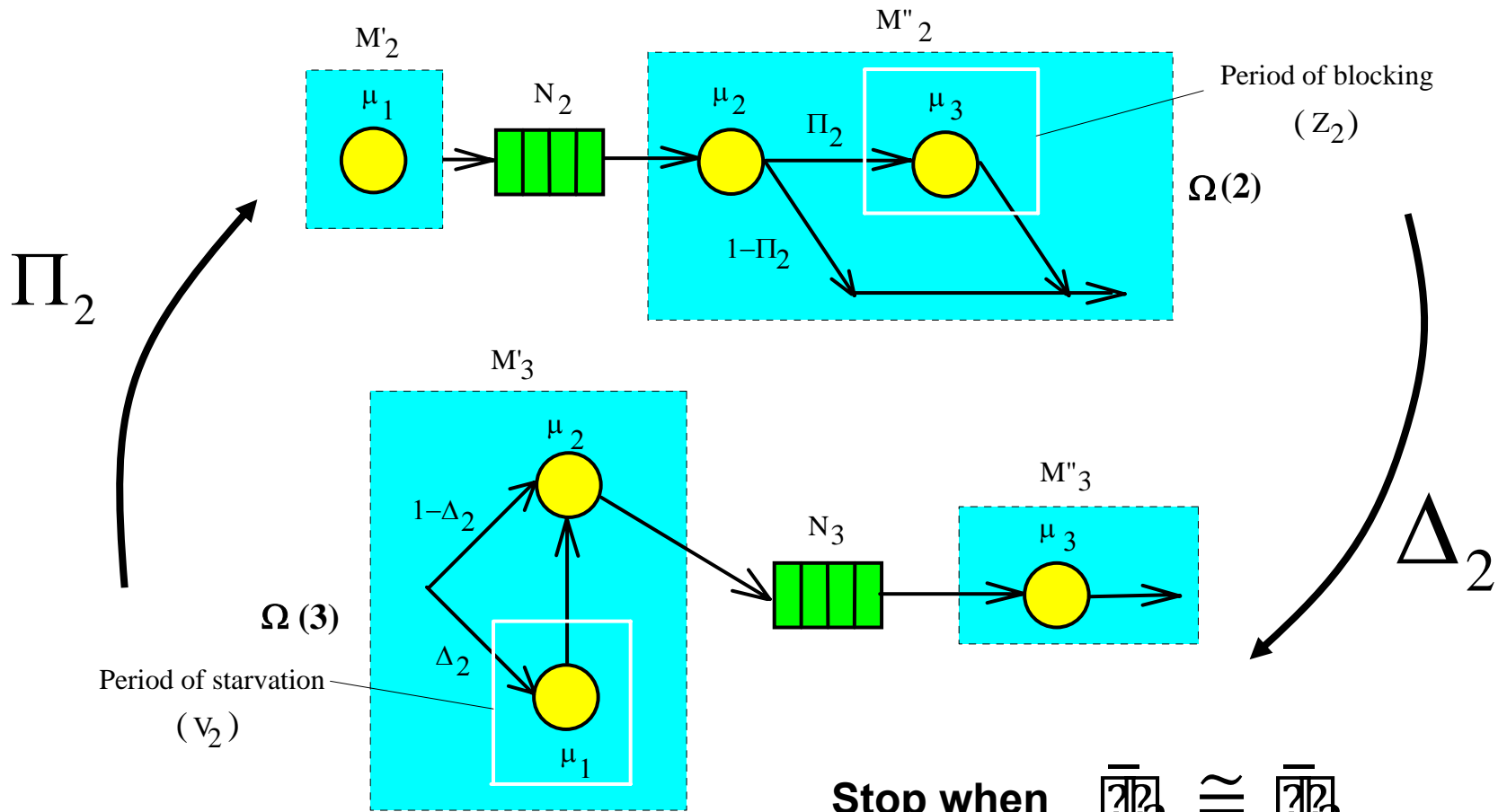
$$\bar{o}_l \Pi_i E[Z_i] = P_i (B)$$

$\Omega(2)$

$$\bar{o}_l \Delta_i E[V_i] = P_i (0),$$

The Iteration

$$\bar{o}_l \Delta_i E[V_i] = P_i(0),$$



$$\bar{o}_l \Pi_i E[Z_i] = P_{i+1}(B)$$

Convergence of the Throughput

$$K = 3$$

$$\mu_i = 2$$

$$N_i = 1$$

Iteration No	Δ_2	Π_2	\bar{o}_i
0	0.1	0.1	-
1	0.47499	-	1.26984
2	-	0.38125	1.07744
3	0.40469	-	1.11986
4	-	0.39883	1.10895
5	0.40029	-	1.11165
6	-	0.39993	1.11098
7	0.40002	-	1.11115
8	-	0.39999	1.11110
9	0.40000	-	1.11111
10	-	0.39999	1.11111

Exact Throughput: 1.1282 [Hunt (1956)]

Numerical Results

5 station Decomposition:

Buffers	\bar{N}_{App}	\bar{N}_{Sim}	Rel. Err
			%
1	3.5095	3.5293	-0.56
2	2.2104	2.3098	-4.3
3	7.4080	6.9328	6.85
4	3.7905	3.7151	2.03

$$\underline{\mu} = (2.5, 4, 3, 2, 5)$$

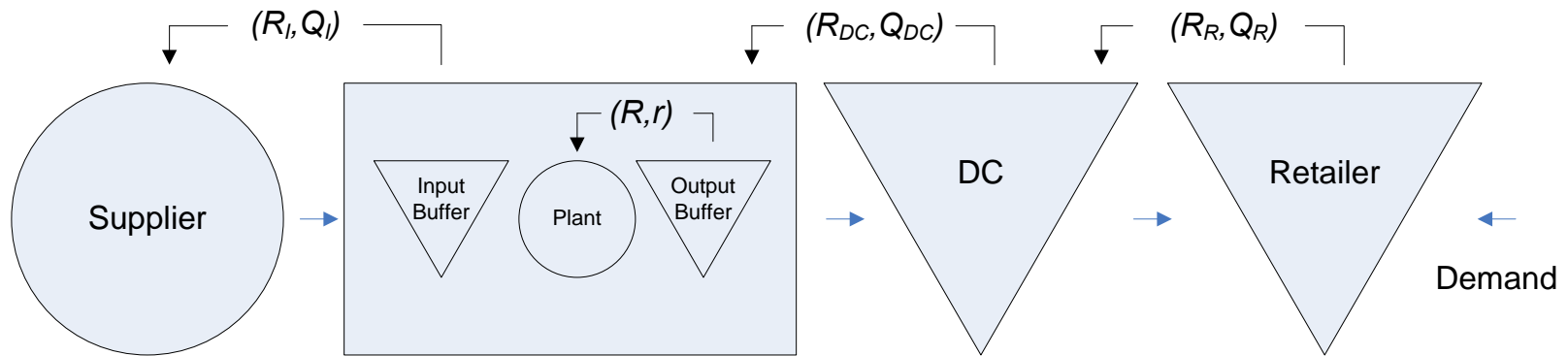
$$\underline{N} = (4, 4, 10, 4)$$

$$Cv^2 = (2.5, 0.25, 3.0, 0.3, 0.75)$$

—
 O_l

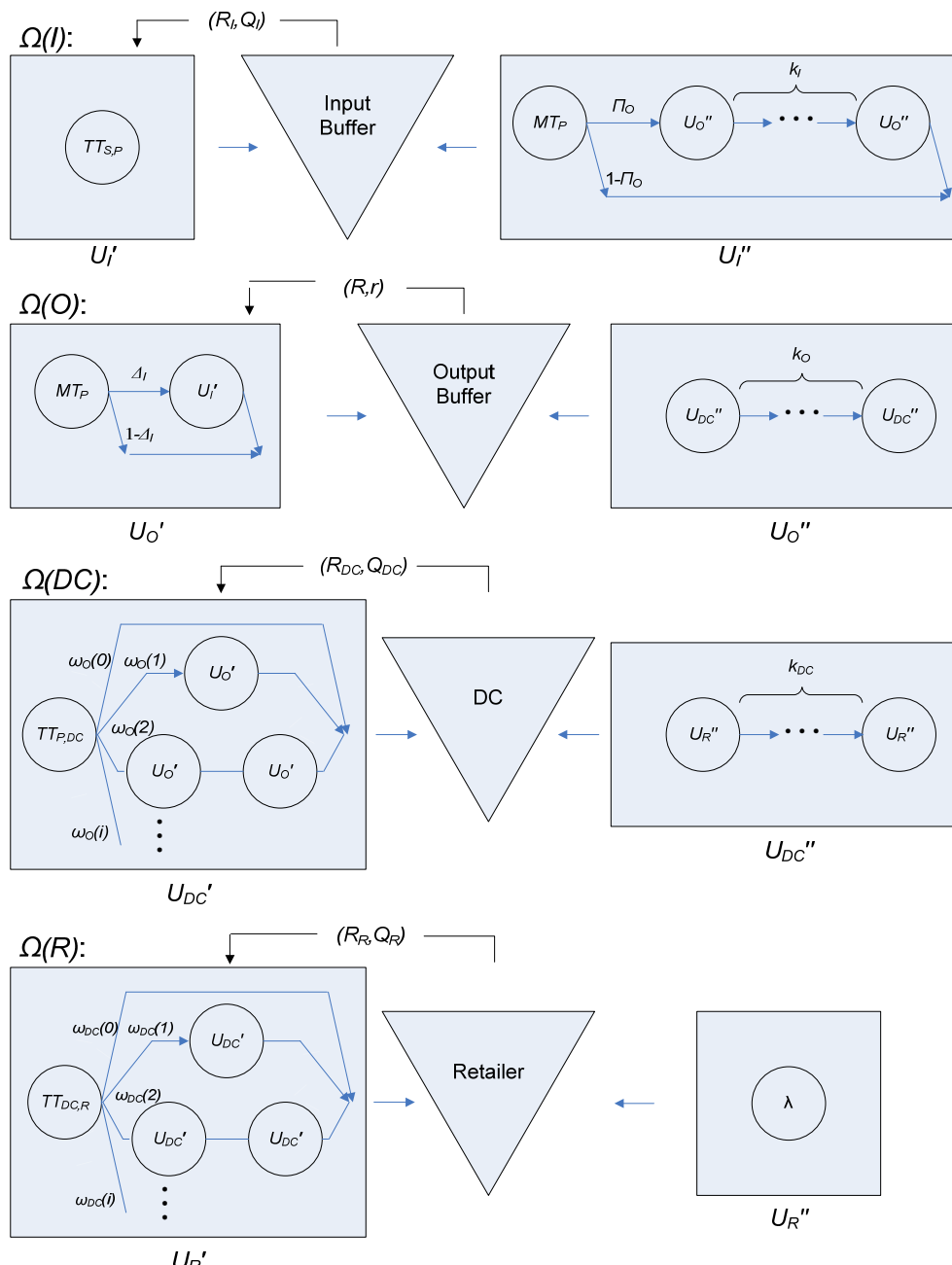
Appx=0.1984
Sim=0.1964

Supply Chain Applications

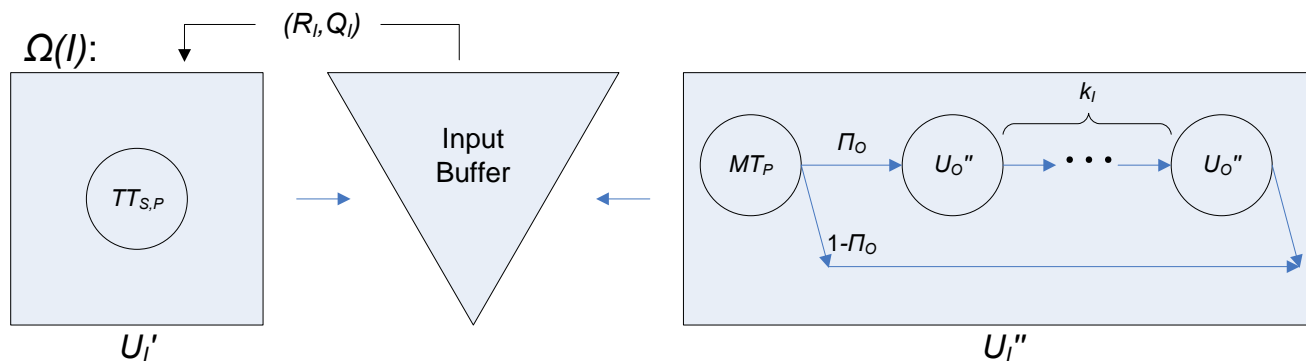


- Single-product
- (R, Q) , (R, r) continuous review policies
- Backordering among echelons
- Several outstanding orders
- General transportation times (PH)

Decomposition



Steady-State Analysis of Subsystems



$$I_t = \begin{cases} i, & U_I' \text{ is in phase } i \quad i=1,2 \\ B, & U_I' \text{ is blocked} \end{cases}$$

$$J_t = \begin{cases} 0, & U_I'' \text{ is starving} \\ i, & U_I'' \text{ is in phase } i \end{cases}$$

$$N_t = 0, 1, 2, \dots, R_I + Q_I$$

$\{ I_t, J_t, N_t, t \geq 0 \}$ Markov chain with a finite number of states.

Computational Accuracy

- Backorder Case

		$R_I = 10$	$R = 30$	$\mu_1 = 2$	$R_{DC} = 10$	$R_R = 5$
Parameters:		$Q_I = 13$	$r = 10$	$\mu_2 = 1$	$Q_{DC} = 20$	$Q_R = 10$

Computational Accuracy

		$\lambda=1.3$		
		Inv. Level	BO Level	Cust. Sat.
Input Buffer	Analytic	14.3861	N/A	99.84%
	Simulation	14.3896	N/A	99.84%
	Rel. Error	-0.02%	N/A	0.00%
<hr/>				
Output Buffer	Analytic	20.2831	0.0515	95.14%
	Simulation	20.3260	0.0495	95.30%
	Rel. Error	-0.21%	4.04%	-0.17%
<hr/>				
DC	Analytic	22.2038	0.0004	99.98%
	Simulation	22.2087	0.0035	99.92%
	Rel. Error	-0.02%	-88.57%	0.06%
<hr/>				
Retailer	Analytic	7.9228	0.0528	96.78%
	Simulation	7.9205	0.0537	96.75%
	Rel. Error	0.03%	-1.68%	0.03%

$\lambda=1.5$		
Inv. Level	BO Level	Cust. Sat.
13.9829	N/A	99.83%
13.9857	N/A	99.80%
-0.02%	N/A	0.03%
<hr/>		
14.7011	1.4737	71.67%
14.7971	1.3927	72.17%
-0.65%	5.82%	-0.69%
<hr/>		
18.7423	0.7061	94.10%
19.5314	0.4381	95.71%
-4.04%	61.17%	-1.68%
<hr/>		
7.0957	0.3687	89.68%
7.3054	0.3470	92.87%
-2.87%	6.25%	-3.43%

Designing Operational Policies

- Complex optimal control policy
 - Restrict the structure of the control policy
 - Use the simple reorder policies at all installations
- Coordinate simple decision rules in the best possible way
 - Minimize steady-state expected total system-wide costs
- Decision variables: $(R_I, Q_I), (R, r), (R_{DC}, Q_{DC}), (R_R, Q_R)$

Designing Operational Policies

Total Cost: Set-up, holding, backordering, shortage cost

- SC: Set-up cost per order
- h: unit holding cost per unit time
- g: unit backordering cost per unit time
- p: shortage cost per unit short
- λ : mean rate of demand

Min Total Cost (Entire System)

$$TC(\underline{Q}, \underline{R}) = \sum_k \frac{SC \times \lambda}{Q} + hE[I] + gE[B] + p\lambda \Pr(\text{Backorder})$$

s.t. $RI, QI, R, r, RDC, QDC, RR, QR$ integer

Optimization

Example

				Input	Output	DC	Retailer
	$\mu_1 = 2$	$\beta_S = 1$	SC	30	25	20	15
$\lambda = 1.5$	$\mu_2 = 1$	$\beta_P = 1$	h	0.2	0.4	0.6	0.8
	$a = 0.1$	$\beta_{DC} = 1$	g		0.6	0.4	0.2
			p	100	10	50	25

Optimization

Example

Input		Output		DC		Retailer		Cost					
Q_I	R_I	R	r	Q_{DC}	R_{DC}	Q_R	R_R	Input	Output	DC	Retailer	TOTAL	Fill Rate
13	10	30	10	20	10	10	5	9.3077	12.8896	17.4546	11.8722	51.524	89.67%
14	9	31	11	20	11	11	6	8.9591	12.892	15.5895	11.5487	48.9892	
		35	13	22	12				12.9953	16.3616		49.8646	
15	8	35	13	22	12	12	5	8.6927	13.108	16.4506	10.9812	49.2324	
		37	13	24	10				13.3169	17.219		50.2099	
16	7	37	13	24	9	12	5	8.4961	13.4786	16.9707	10.9483	49.8937	
		37	13	24	7				13.4786	15.8918		48.8148	
17	6	38	14	24	6	12	5	8.3861	13.7273	15.7524	11.1456	49.0115	
		38	14	24	4				13.7273	14.688		47.9471	
17	6	38	14	24	3	12	5	8.3821	13.7285	14.159	11.1474	47.417	
		38	14	24	1				13.7285	13.0948		46.3528	
17	6	38	14	24	1	12	5	8.3821	13.7285	13.0948	11.1474	46.3528	
		38	14	24	1				13.7285	13.0948		46.3528	
													Fill Rate
17	6	38	14	24	1	12	5	8.3821	13.7285	13.0948	11.1474	46.3528	93.05%

Any Questions?