

Parameter Estimation in Large-Scale Optimization Models

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International Colloquium on Stochastic Modeling and Optimization Dedicated to the 80th birthday of Professor András Prékopa

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General Theme

- As optimization models grow, so do the number of estimated or sampled parameters
- The chance of rare estimation events increases (close to 1)
- Optimization models are driven to extremes and naturally focus on "rare events" that slow convergence (or increase errors) and increase dependence on dimension
- *Challenge:* Can we find a way to avoid these problems? (Better ways to use available data?)

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Example: Financial Portfolio Optimization

Quadratic program (Markowitz Portfolio):

find investments x=(x(1),...,x(n)) to

 $\min x^{\scriptscriptstyle T} \, Q \, x$

s.t. $r^T x = target, e^T x=1$

where Q and r are typically estimated from historical data.

Correlations from University of Michigan CIO:

	DomCommon	SmallCap	InteCommon	EmerMarkets	AbsoluteRetur	VentCap	RealEst	Oil and Gas	Commodities	FixedIncome	IntFixedInc
DomCommon	1	0.79	0.58	0.56	0.6	0.44	0.25	0.01	-0.3	0.43	0.2
SmallCap	0.79	1	0.48	0.61	0.65	0.56	0.24	0.01	-0.05	0.31	0.1
InteCommon	0.58	0.48	1	0.37	0.45	0.25	0.38	-0.04	-0.17	0.35	0.55
EmerMarkets	0.56	0.61	0.37	1	0.3	0.3	0.07	-0.19	-0.07	-0.07	0.1
AbsoluteRetur	0.6	0.65	0.45	0.3	1	0.35	0.2	-0.2	0.11	0.35	0.25
VentCap	0.44	0.56	0.25	0.3	0.35	1	0.21	-0.02	-0.18	0.19	0.15
RealEst	0.25	0.24	0.38	0.07	0.2	0.21	1	0.08	-0.53	0.15	0.2
Oil and Gas	0.01	0.01	-0.04	-0.19	-0.2	-0.02	0.08	1	0.54	-0.18	-0.3
Commodities	-0.3	-0.05	-0.17	-0.07	0.11	-0.18	-0.53	0.54	1	-0.3	-0.08
FixedIncome	0.43	0.31	0.35	-0.07	0.35	0.19	0.15	-0.18	-0.3	1	0.55
IntFixedInc	0.2	0.1	0.55	0.1	0.25	0.15	0.2	-0.3	-0.08	0.55	1
Cash	0.27	0.08	0.23	0.04	0.45	0.14	0.37	-0.07	-0.13	0.67	0.1



	Amt. to invest
DomCommon	-54079107483.07
SmallCap	-17314640179.88
InteCommon	-7098209713.34
EmerMarkets	21285151081.48
AbsoluteReturn	65911278495.65
VentCap	3346118938.17
RealEst	-68300117027.99
Oil and Gas	66227880616.79
Commodities	-104263997812.77
FixedIncome	-72656761795.57
IntFixedInc	117884874179.2
Cash	49057530702.32
Return	0.1
Variance	-1.65E+019

What happened here?



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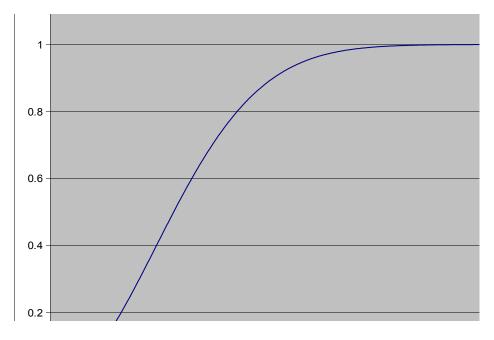


Problems in Markowitz Model

- Consistent time series
 - Correlations from different time series may not yield PD covariance matrices
 - Caution for general parameter estimates
- Number of Correlation Parameters
 - For *n* assets, n(n-1)/2 correlations to estimate
 - Chances of estimation error increase rapidly in

CHICAGOBOOTH of Negative Correlation Observations

- Assume all true correlations are 3 standard deviations above 0 and each estimate is independent (not so but..)
- How does the probability of negative correlation observation relate to n (no. of assets)?





Problem Statement

- Large problems with *n* variables and *m* constraints/objective coefficients lead to (at least) *mn* estimates
- Probability of significant deviation from mean values increases rapidly in *mn*
- Deviant estimates drive optimal solutions
- How can we construct large models that yield consistent results with high probability?

CHICAGO BOOTH The General Questions

• Consider the basic problem (stochastic program):

 $\operatorname{Min}_{x \in X} E_{\boldsymbol{\xi}}[f(x, \boldsymbol{\xi})] \qquad (P)$

- Suppose the only information for ξ is through samples: ξ¹,...,ξ^v
- What can we say about solutions of sampled problems:

$$Min_{x \in X} (1/\nu) \sum_{i=1}^{\nu} f(x, \xi^i)$$

in relation to solution x^* to (P)?

• Are there better ways to use those samples?



General Sampling Result

(King-Rockafellar (1993, e.g.): Suppose x^{ν} solves: $\min_{x \in X} (1/\nu) \sum_{i=1}^{\nu} f(x, \xi^i)$

- then, under a suitable set of conditions (X polyhedral, *f* smooth, unique optimum),
- we can find a random vector, *u*, that solves another optimization problem such that

 $V^{0.5}(\mathbf{x}^{\mathbf{v}} - \mathbf{x}^*)$ converges to \mathbf{u}

Note: similar to a Central Limit Theorem but maybe even better. u is often Gaussian but often projected onto constraints.



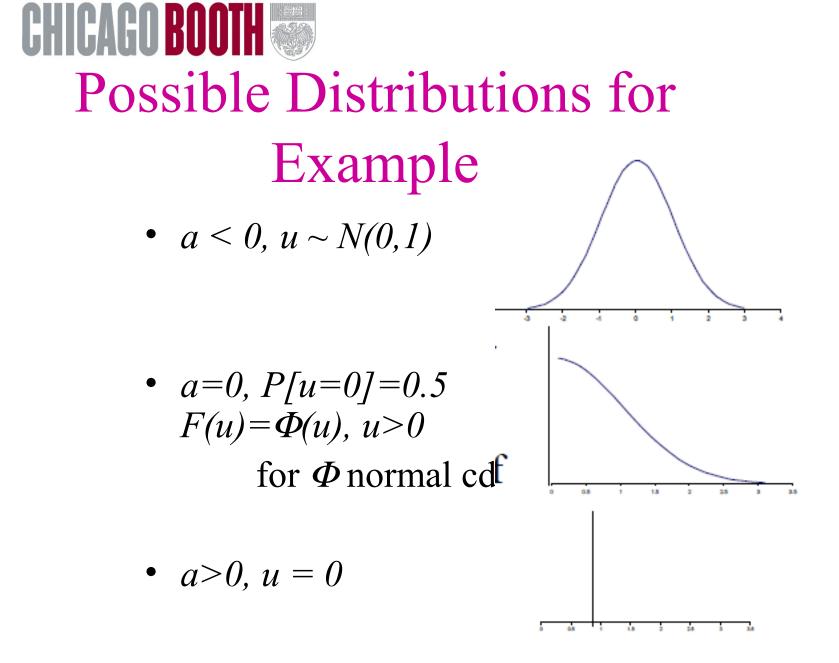
Example of Asymptotic Distribution

- The asymptotic distribution of *u* depends on the constraints
- Example: Find x to

$$\min_{x \ge a} E[|| x - \xi ||]$$

where $\xi \sim N(0,1)$.
Note: $x^* = a$ for $a \ge 0$. 0 for $a \le 0$.

What is the value of u ~ lim_v v^{0.5}(x^v - x^{*}) for different a?





Observations: The Good News

- Asymptotic distribution of optimal solution of sampled problem is:
 - Sometimes multivariate normal
 - Sometimes projection of multivariate normal onto constraints
 - Sometimes an atom at a single point
- Questions for large data sets:
 - When do we start to observe the asymptotic behavior?
 - How big must v (no. of samples) be?



Quantitative Results Goal: *Universal Confidence Sets* (e.g., Pflug (2003), Vogel (2008))

$$P\{|E_{\xi}[f(x^{\nu},\xi) - f(x^*,\xi)]| \ge \epsilon\} \le \alpha_1 e^{-\beta_1 \nu}.$$

and, if x^* is unique,

$$P\{\|x^{\nu} - x^*\| \ge \epsilon\} \le \alpha_0 e^{-\beta_0 \nu}.$$

Possible (sometimes explicit), e.g., Dai, Chen, JRB (2000)

CHICAGO BOOTH S Observations and Questions Have appealing asymptotic results that

- indicated confidence intervals might be possible
- Have universal bounds that indicate exponential convergence
- Questions: 1. When do asymptotic properties appear? (Size of the constants?)
- 2. What are the effects of dimension? of multiple uncertainties? of constraints?
- 3. Are there better ways to use samples and, if so, when?

Form of Examples: Mean-Risk

Objective is composed of risk and return: E[f(x,w)] = -exp.return(x) + risk(x)For portfolios, often mean-variance, but can be different.

For uncertainty, sometimes only in the return, sometimes only in risk and sometimes in both – (this can effect convergence)



Example Problem

- Consider the following problem:
- $min_{x} E_{\varepsilon} \int -\boldsymbol{\xi}^{T} \boldsymbol{x} + \boldsymbol{\varepsilon} || \boldsymbol{x} ||_{1} \int$
- s. t. $-1 \le x \le 1$

where $\| . \|_1$ is the 1-norm (so equivalent to a linear program) and $E[\boldsymbol{\xi}]=0.$

The optimal solution should be $x^*=0$.

How long to achieve limiting distribution?

How long will it take a sample solution to approach x^* exponentially? i.e., when does $Log(P_{i}||x^{v}-x^{*}|| \geq \varepsilon)$ decrease linearly? Prékopa Colloquium, Dec. 1, 2009 © JRBirge

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Sample Problem

• Assume that $\xi_j \sim N(0,1)$ for all j,

the solution is $x^{\nu_j} = 0$ if $|\xi_j| \le \varepsilon$, and ± 1 o.w.

So,
$$P\{||x^{\nu}-x^*|| \ge l\} = P\{|x^{\nu}| \ge 1, \text{ some } j\}$$

=
$$P\{|\xi_j| \ge \varepsilon, \text{ some } j\} = 1 - (1 - 2\Phi(-\gamma v^{0.5}))^n$$

where Φ is the standard normal c.d.f.

Note: already normal

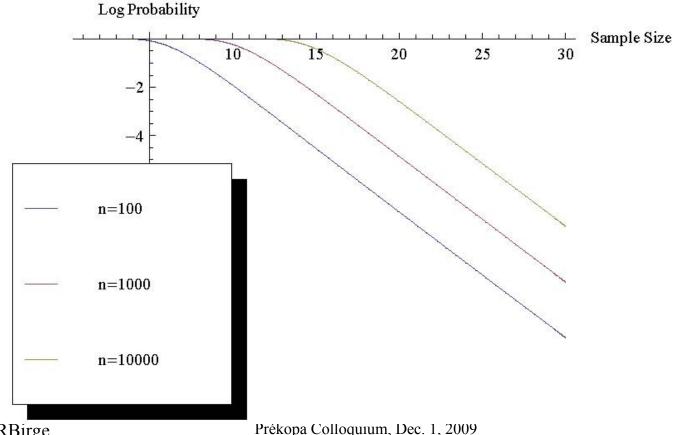
When is $Log(P(error \ge 1))$ linear in v?

What is the effect of dimension? (Note n)



Results

Log (P(error >1)) v. sample size (v)





Observations

- Some delay in approach to exponential error decrease with dimension
- Increase in the delay (size of the constants in the universal bound) is less than linear in dimension (in fact, less than linear in Log of dimension)
- Same kinds of effects for objective
- Good results but could they be even better? Can we reduce the effect of the dimension?

CHICAGU BUUIH How Can We Reduce the Required Number of Samples?

- Use of sub-samples or batch mean
- Suppose that we divide the *v* samples into *k* batches of *v/k* each, let ξ^v_i be the mean of batch *i=1,...,k*, then solve with ξ^v_i to obtain x^v_i
- Let $x^{v,k} = (1/k) \sum_{i=1}^{k} x^{v_i}$
- Can this do better?
- In particular, can we do better in the worst case?



Result for Sub-sample Batch Optimization

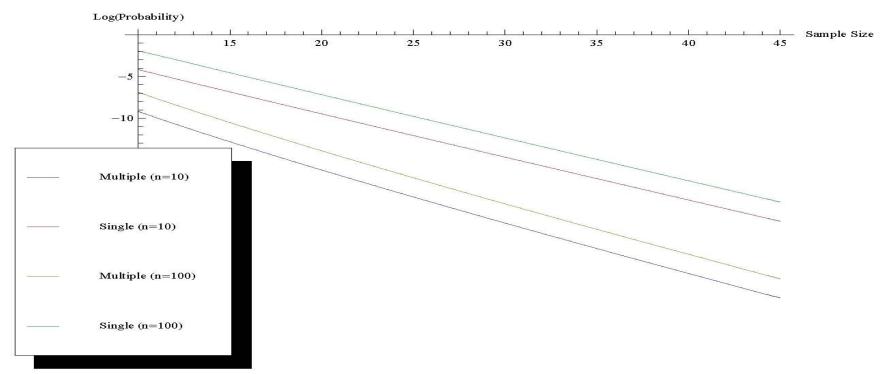
• What is the chance that one component in the decision variable is far off?

$$P\{\|x^{\nu/K,K} - x^*\|_{\infty} \ge 1\} \le P\{|x_j^{\nu,i}| \ge 1, \forall i = 1, \dots, K; \text{ for some } j \in \{1, \dots, n\}, \}$$
$$= 1 - (1 - (2\Phi(-\gamma(\nu/K)^{0.5}))^K)^n,$$

• Now, decreased dependence on *n*



Results for Batch/Single Samples



Observe: more improvement as $v \uparrow$ (from 4 to 9 orders of magnitude)

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What about Effects of Uncertainty in Risk?

• Example:

$$\min_{\|x\|_2 \le 1} E[-\xi^T x + \frac{\gamma}{2} \|x\|_2^2],$$

- Now, ξ and γ are random Suppose $\xi_j \sim N(0,1)$; $\gamma \sim N(1,1)$
- Unconstrained solution:

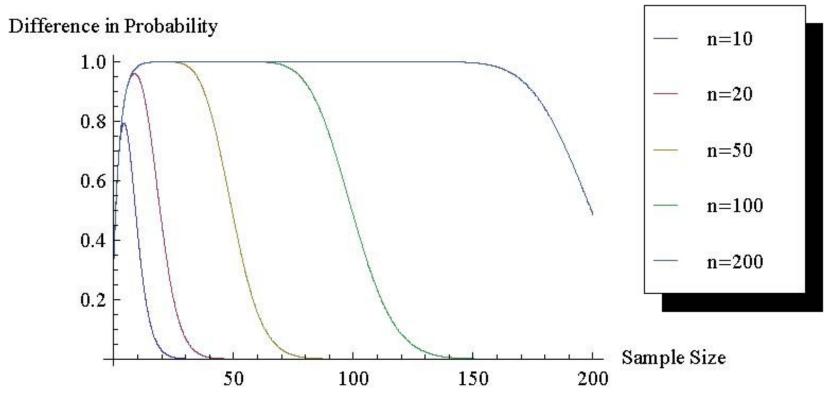
Error in solution in 2-norm is χ^2 under asymptotic distribution True error in solution is given by:

$$\frac{1}{\|x^{\nu,u} - x^*\|_2^2} \sim F(1, n, \nu),$$

where F is the non-central F-ratio distribution

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CHICAGO BOOTH How Many Samples before the Error Approaches Asymptotic Distribution?





Observations

- Convergence now is much slower than in the case with just stochastic returns
- Convergence delay to the asymptotic distribution is almost linear in dimension
- Asymptotic distribution for the objective is again similar
- Asymptotic distribution for the general portfolio problem with multiple variance estimates (and inverse Wishart distribution) is even worse



Full Portfolio Examples

• General form:

$$\min_{x \in X} -\bar{r}^T x + \frac{\gamma}{2} x^T \Sigma x.$$

requires estimation: e.g., using sample estimates as:

$$\min_{x \in X} -\hat{r}^T x + \frac{\gamma(\nu - n - 2)}{2\nu} x^T \hat{\Sigma} x$$

and (v-n-2)/v term makes solution un-biased with no constraints (e.g., Kan and Zhou (2007))



Questions to Consider

- Can the use of sub-sample/batch optimal solutions improve convergence?
- How do the constraints affect the performance of the batch solution approximations?
- What is the effect of dimension in these problems?



Simulation Setup

For these results, we suppose n = 10, $\nu = 500$, and K = 10 and let $\gamma = 1$, $\mu = 0.2e$, where $e = (1, \ldots, 1)^T$, and $\Sigma = 0.05 * I$, where I is an identity matrix. We present the results from 1000 simulation runs for three different sets, X, corresponding to increasing ranges on x: $[0, 1]^{10}$, $[-1, 2]^{10}$, and $[-5, 10]^{10}$. The results are compared relative to the optimal solution $x^* = 0.4e$ in terms of $||x^{\nu} - x^*||/||x^*||$ and optimal objective value $z^* = -\bar{r}^T x^* + \frac{1}{2}x^{*T}\Sigma x^* = -0.04$ in terms of $(-\bar{r}^T x^{\nu} + \frac{1}{2}(x^{\nu})^T\Sigma x^{\nu} - z^*)/(-z^*)$.

Observe: histograms of relative errors in solutions and losses in objective



 $X = [0, 1]^{10}$

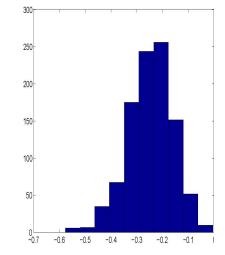
Relatives differences:

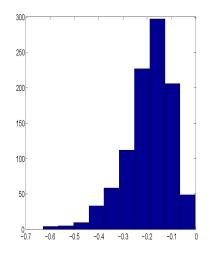
Batch better: 1000/1000

Avg. Sol. Dist. Diff. : -25%

Solution

Objective





Avg. Obj. Diff.: -19% © JRBirge CHICAGO BOOTH

 $X = [-1,2]^{10}$

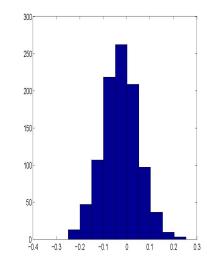
Relatives differences:

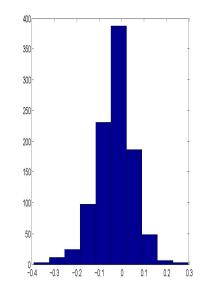
Batch better: 638/1000

Avg. Sol. Dist. Diff. : -3%



Objective





Avg. Obj. Diff.: -3% © JRBirge



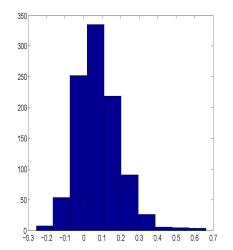
X=[-5,10]¹⁰ Relatives differences:

Batch better: 231/1000

Avg. Sol. Dist. Diff. : +7%

Solution

Objective



Avg. Obj. Diff.: +8%

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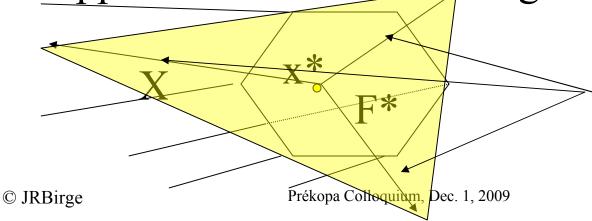
Observations on Portfolios

- Batch approach improves when constraints can bind the sample solutions
- The batch improvement is significant when constraints are relatively tight (but still more than 3 standard deviations from optimum)
- Batch can improve without constraints (but not so much in low dimensions ~10)



General Implications?

- How to put the batch results in terms of universal bounds?
- View: consider errors distributed throughout X and decompose by cone support in face F* containing x*



Positive basis of aff (F*)



Assumptions

- Under mild conditions, x* is randomly distributed in F*
- Assume bias is known (or bounded)

$$b_{\nu/K} = \|E[x^{\nu/K} - x^*]\|$$
 $O((\nu/K)^{-\frac{1}{2n}})$

- under certain regularity conditions (e.g., Roemisch and Schulz (1991))
- Worst error in any direction is g/n.



General Result

• Under these conditions,

$$P(\|\bar{u}^{\nu,K}\| \ge b_{\nu/K} + \frac{aM((N+1)g(N-g))^{1/2}}{K^{1/2}N}) \le \frac{1}{a^2+1}.$$

• So, if unbiased, $a=K^{1/4}$,

error is greater than $\frac{g^{1/2}M}{K^{1/4}}$ with probability at most $\frac{1}{\sqrt{K+1}}$.

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Implications of Result

- For relatively symmetric regions, the error from using batches can be of order even when asymptotics are not achieved within each sub-sample
- Non-symmetric regions may present difficulties (v \rightarrow 1/2n, worst case: isolated point)

F*:



Comparison to Other Approaches

- Imposing constraints (Jagannathan and Ma (2003))
- Shrinking variance (similar)
- "Re-sampled portfolio" (Michaud) similar
- Robust optimization
- Bayesian updating
- Robust estimation
- Simple rules



Summary Observations

- Convergence to asymptotic behavior may be much slower with optimization and different uncertainty forms than simple estimation
- Dimension has more effect with greater uncertainty
- Use of optimization in batches can improve estimates especially with potentially violated constraints and symmetric feasible regions



Additional Questions

- Does the batch sample continue to improve with dimension in practical problems?
- Can these universal confidence sets be identified in the data?
- Are more general confidence interval estimates available?
- How do these approaches perform with other techniques to enhance convergence?



Thank You and Happy Birthday, András!