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A METHOD OF DISAGGREGATION FOR
BOUNDING PROBABILITIES OF
BOOLEAN FUNCTIONS OF EVENTS

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A METHOD OF DISAGGREGATION FOR BOUNDING PROBABILITIES OF BOOLEAN FUNCTIONS OF EVENTS

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Abstract. Given a sequence of n arbitrary events, we assume that the individual probabilities as well as the joint probabilities of up to m events are known, where $m < n$. Using this information, a simple and frequently efficient method to give lower and upper bounds for Boolean functions of the events, is the univariate discrete moment problem. In order to obtain better bounds we subdivide the event sequence into subsequences and use the multivariate discrete moment problem for bounding. This way the information regarding the known probabilities is better exploited and we may keep the problem sizes moderate. Numerical results show the efficiency of this approach.

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1 Introduction

Let A_1, \dots, A_n be arbitrary events in some probability space, and introduce the notations

$$P(A_{i_1} \cap \dots \cap A_{i_k}) = p_{i_1 \dots i_k}, \quad 1 \leq i_1 < \dots < i_k \leq n,$$

$$S_k = \sum_{1 \leq i_1 < \dots < i_k \leq n} p_{i_1 \dots i_k}, \quad k = 1, \dots, n.$$

Let $S_0 = 1$, by definition. If ν designates the number of those events (among A_1, \dots, A_n) which occur, then we have the relation:

$$E \left[\binom{\nu}{k} \right] = S_k, \quad k = 0, \dots, n. \quad (1)$$

The equations (1) can be written in the more detailed form

$$\sum_{i=0}^n \binom{i}{k} v_i = S_k, \quad k = 0, \dots, n,$$

where $v_i = P(\nu = i)$, $i = 0, \dots, n$.

The values (1) are called the binomial moments of ν . If we know all binomial moments of ν , then the probabilities v_0, \dots, v_n , and also the value of any linear functional acting on the probability distribution v_0, \dots, v_n , can be determined. If, however, we only know S_1, \dots, S_m , where $m < n$, then linear programming problems provide us with lower and upper bounds on the true value of this functional. We formulate two closely related types of linear programming problems (see Prékopa (1988, 1990a,b)):

$$\begin{aligned} & \min(\max) \sum_{i=1}^n c_i x_i \\ & \text{subject to} \\ & \sum_{i=1}^n \binom{i}{k} x_i = S_k, \quad k = 1, \dots, m \\ & x_i \geq 0, \quad i = 1, \dots, n, \end{aligned} \quad (2)$$

and

$$\begin{aligned} & \min(\max) \sum_{i=0}^n c_i x_i \\ & \text{subject to} \\ & \sum_{i=0}^n \binom{i}{k} x_i = S_k, \quad k = 0, \dots, m \\ & x_i \geq 0, \quad i = 0, \dots, n. \end{aligned} \quad (3)$$

These provide us with lower and upper bounds on the linear functionals $\sum_{i=1}^n c_i v_i$, and $\sum_{i=0}^n c_i v_i$, respectively. Note that the first constraint in problem (3) does not appear in problem (2). The following objective functions are of particular interest:

$$c_0 = c_1 = \dots = c_{r-1} = 0, \quad c_r = \dots = c_n = 1, \quad 1 \leq r \leq n \quad (4)$$

$$c_r = 1, \quad c_i = 0 \text{ for } i \neq r, \quad 0 \leq r \leq n. \quad (5)$$

If we use the objective function coefficient (4) in the linear programs (2), (3), then the optimum values provide us with lower and upper bounds for the probability that at least r out of n events occur. The objective function with coefficients (5) provides us with bounds for the probability that exactly r events occur. Any dual feasible basis of any of the problems (2) and (3) provides us with a bound. The best bound corresponds to the optimal basis which is both primal and dual feasible, and is called sharp.

Lower and upper bounds for the probability that at least one out of n events occurs, based on the knowledge of S_1, \dots, S_m , were found by Bonferroni (1937). These bounds are not sharp. For the case of $m = 2$, sharp lower bound for the probability that at least one out of n events occurs was proposed by Dawson and Sankoff (1967). For the case of $m \leq 3$, Kwerel (1975a,b) has obtained sharp lower and upper bounds. He applied linear programming theory in his proofs. For the case of $m = 2$ other results are due to Galambos (1977), and Sathe, Pradhan and Shah (1980). For a general m , the linear programs with objective functions (4), and (5) have been formulated and analyzed by Prékopa (1988, 1990a,b). He also presented simple dual type algorithms to solve the problems. Boros and Prékopa (1989) utilized the results and presented closed form bounds.

Problems (2), and (3) use the probabilities $p_{i_1 \dots i_k}$ in aggregated forms, i.e., S_1, \dots, S_m are used rather than the probabilities in these sums. This way we trade information for simplicity and size reduction of the problems. We call (2) and (3) aggregated problems.

The linear programs which make us possible to use the probabilities $p_{i_1 \dots i_k}$, $1 \leq i_1 < \dots < i_k \leq n$ individually, will be called disaggregated, and can be formulated as follows. Let D_1 be the $n \times 2^n - 1$ matrix, the columns of which are formed by all 0,1-component vectors which are different from the zero vector.

Let us call the collection of those columns of D_1 , which have exactly k components equal to 1, the k^{th} block, $1 \leq k \leq n$. Assume that the columns in D_1 are arranged in such a way that first come all vectors in the first block, then all those in the second block, etc. Within each block the vectors are assumed to be arranged in

a lexicographic order, where the 1's precede the 0's. Let d_1, \dots, d_n designate the rows of D_1 , and define the matrix $D_k, 2 \leq k \leq m$, as the collection of all rows of the form: $d_{i_1} \dots d_{i_k}$, where the product of the rows d_{i_1}, \dots, d_{i_k} is taken componentwise. Assume that the rows in D_k are arranged in such a way that the row subscripts (i_1, \dots, i_k) admit a lexicographic ordering, where smaller numbers precede larger ones. Let

$$A = \begin{pmatrix} D_1 \\ \cdot \\ \cdot \\ \cdot \\ D_m \end{pmatrix}.$$

In addition, we define the matrix \hat{A} by

$$\hat{A} = \begin{pmatrix} 1 & \mathbf{1}^T \\ 0 & D_1 \\ \cdot & \cdot \\ \cdot & \cdot \\ \cdot & \cdot \\ 0 & D_m \end{pmatrix},$$

where $\mathbf{1}$ is the $2^n - 1$ -component vector, all components of which are 1, and the zeros in the first column mean zero vectors of the same sizes as the numbers of rows in the corresponding D_i matrices.

Let $p^T = (p_{i_1 \dots i_k}, 1 \leq i_1 < \dots < i_k \leq n, k = 1, \dots, m)$, where the order of the components follow the order of the rows in A , and $\hat{p}^T = (1, p^T)$. The disaggregated problems are:

$$\begin{aligned} & \min(\max) f^T x \\ & \text{subject to} \\ & Ax = p \\ & x \geq 0, \end{aligned} \tag{6}$$

and

$$\begin{aligned} & \min(\max) \hat{f}^T \hat{x} \\ & \text{subject to} \\ & \hat{A}\hat{x} = \hat{p} \\ & \hat{x} \geq 0, \end{aligned} \tag{7}$$

where $\hat{f}^T = (f_0, f^T), \hat{x}^T = (x_0, x^T)$.

The duals of the above problems are:

$$\begin{aligned} & \max(\min) p^T y \\ & \text{subject to} \\ & A^T y \leq (\geq) f, \end{aligned} \tag{8}$$

and

$$\begin{aligned} & \max(\min) \hat{p}^T \hat{y} \\ & \text{subject to} \\ & \hat{A}^T \hat{y} \leq (\geq) \hat{f}, \end{aligned} \tag{9}$$

where $\hat{y}^T = (y_0, y^T)$. Since the dual vector y multiplies the vector p in problem (8), it is appropriate to designate the components of y by $y_{i_1 \dots i_k}$, $1 \leq i_1 < \dots < i_k \leq n$, $k = 1, \dots, m$.

If we construct bounds on $P(A_1 \cup \dots \cup A_n)$, then we should take $f^T = (1, \dots, 1)$, and $\hat{f}^T = (0, f^T)$ in the above problems. In this case the more detailed form of problems (8) is the following:

$$\begin{aligned} & \max(\min) \sum_{k=1}^m \sum_{1 \leq i_1 < \dots < i_k \leq n} p_{i_1 \dots i_k} y_{i_1 \dots i_k} \\ & \text{subject to} \end{aligned} \tag{10}$$

$$\sum_{k=1}^m \sum_{1 \leq i_1 < \dots < i_k \leq n} y_{i_1 \dots i_k} \leq (\geq) 1.$$

The more detailed form of problem (9) is the following:

$$\begin{aligned} & \max(\min) \left\{ y_0 + \sum_{k=1}^m \sum_{1 \leq i_1 < \dots < i_k \leq n} p_{i_1 \dots i_k} y_{i_1 \dots i_k} \right\} \\ & \text{subject to} \end{aligned} \tag{11}$$

$$y_0 + \sum_{k=1}^m \sum_{1 \leq i_1 < \dots < i_k \leq n} y_{i_1 \dots i_k} \leq (\geq) 1. \tag{12}$$

The above probability approximation scheme was first proposed by George Boole (1854). A detailed account on it was presented by Hailperin (1956). Kounias and Marin (1976) made use of problem (11) to generate bounds for the case of $m = 2$.

Concerning problems (6), (7), (8) and (9) the following objective functions are of particular interest:

$$f_i = \begin{cases} 1 & \text{if } i \text{ corresponds to a column in } D_1 \text{ which has at least } r \text{ 1's} \\ 0 & \text{otherwise,} \end{cases} \tag{13}$$

and

$$f_i = \begin{cases} 1 & \text{if } i \text{ corresponds to a column in } D_1 \text{ which has exactly } r \text{ 1's} \\ 0 & \text{otherwise.} \end{cases} \quad (14)$$

If we take the objective function given by (12), then the optimum value of the minimization (maximization) problem (7) gives lower(upper) bound for the probability that at least r out of the n events occur. If we take the objective function given by (13), then the optimum value of the minimization(maximization) problem (7) gives lower(upper) bound for the probability that exactly r out of the n events occur. Any dual feasible basis of any of the above problems provides us with a bound. The sharp (best) bounds correspond to optimal bases.

In case of the objective function (12), $r = 1$, the optimum values of the minimization problems (6) and (7) are the same. The optimum values of the maximization problems (6) and (7) are the same provided that the optimum value corresponding to (6) is smaller than or equal to 1. Otherwise, they are different but in that case we should take 1 as the sharp upper bound.

2 Connection Between the Aggregated and Disaggregated Problems

Any feasible solution of problem (6) gives rise, in a natural way to a feasible solution of problem (2). Similarly, any feasible solution of problem (7) gives rise to a feasible solution of problem (3).

Conversely, any feasible solution of the aggregated problem (2) or (3) gives rise to a feasible solutions of the corresponding disaggregated problem. In fact, we obtain problem (6) or (7) from problem (2) or (3) in such a way that we split rows and columns. Splitting a column in the aggregated problem means its representation as a sum of columns taken from the corresponding disaggregated problem.

Another question is that which bases in the aggregated problem produce bases in the disaggregated problem. Consider problem (2) for the case $m = 2$. Then, in the corresponding disaggregated problem we have $n + \binom{n}{2}$ rows. The i^{th} and j^{th} columns in problem (2) split into $\binom{n}{i}$ and $\binom{n}{j}$ columns, respectively. A

necessary condition that these columns form a basis in problem (6) is that $\binom{n}{i} + \binom{n}{j} = n + \binom{n}{2}$, where $i < j$. This condition holds if $i = 1$ and $j = 2$, or $i = n - 2$ and $j = n - 1$. On the other hand these are in fact bases in problem (6), as it is easy to see.

The structures of the dual feasible bases of problems (2) and (3) have been discovered by Prékopa (1988, 1990a,b) for the cases of the objective functions (4), (5) and some others, too. We recall one theorem of this kind.

Theorem 2.1 *Let a_1, \dots, a_n designate the columns of the matrix of problem (2), $I \subset \{1, \dots, n\}$, $|I| = m$, and assume that the objective function coefficients are: $c_1 = \dots = c_n = 1$. Then, $\{a_i, i \in I\}$ is a dual feasible basis if and only if I has the structure:*

$$\begin{array}{ll} \min \text{ problem} & \begin{array}{ll} m \text{ even} & m \text{ odd} \\ i, i+1, \dots, j, j+1 & i, i+1, \dots, j, j+1, n \end{array} \\ \max \text{ problem} & \begin{array}{ll} 1, i, i+1, \dots, j, j+1, n & 1, i, i+1, \dots, j, j+1. \end{array} \end{array}$$

□

In view of this theorem, the first $n + \binom{n}{2}$ columns of the matrix of problem (6), i.e. the columns in the first two blocks, form a dual feasible basis. Similarly, the $n + \binom{n}{2}$ columns in the second to the last, and third to the last blocks of problem (6) form a dual feasible basis. The corresponding dual vectors can be computed from the equations produced by the aggregated problems:

$$(y_1, y_2)(a_1, a_2) = (1, 1),$$

and

$$(y_1, y_2)(a_{n-2}, a_{n-1}) = (1, 1),$$

respectively. The detailed forms of these equations are:

$$\begin{array}{rcl} y_1 & = & 1 \\ 2y_1 + y_2 & = & 1 \end{array}$$

and

$$\begin{array}{rcl} (n-2)y_1 + \binom{n-2}{2}y_2 & = & 1 \\ (n-1)y_1 + \binom{n-1}{2}y_2 & = & 1, \end{array}$$

respectively. The first system of equations gives $y_1 = 1$, $y_2 = -1$, and the second one gives: $y_1 = 2/(n-1)$, $y_2 = -2/(n-1)(n-2)$. If we assign $y_1 = 1$ to all vectors in the first block and $y_2 = -1$ to all vectors in the second block of problem (6), then we obtain the dual vector corresponding to the first dual feasible disaggregated basis. Similarly, if we assign $y_1 = 2/(n-1)$ to all vectors in block $n-2$ and $y_2 = -2/(n-2)(n-1)$ to all vectors in block $n-1$ of problem (6), then we obtain the dual vector to the other dual feasible disaggregated basis. The first dual vector gives the Bonferroni lower bound:

$$P(A_1 \cup \dots \cup A_n) \geq \sum_{i=1}^n p_i - \sum_{1 \leq i < j \leq n} p_{ij} = S_1 - S_2.$$

The second dual vector gives the lower bound

$$P(A_1 \cup \dots \cup A_n) \geq \frac{2}{n-1} S_1 - \frac{2}{(n-2)(n-1)} S_2.$$

The optimal lower, produced by the aggregate problem (2), bound corresponds to that dual feasible basis (a_i, a_{i+1}) which is also primal feasible. This gives $i = 1 + \lfloor 2S_2/S_1 \rfloor$, and the bound is:

$$P(A_1 \cup \dots \cup A_n) \geq \frac{2}{i+1} S_1 - \frac{2}{i(i+1)} S_2.$$

This formula was first derived by Dawson and Sankoff (1967).

If we want to find the sharp lower bound for $P(A_1 \cup \dots \cup A_n)$, by the use of problem (6) for $m = 2$, then we may start from any of the above mentioned two dual feasible bases and use the dual method of linear programming, to solve the problem. Since we want lower bound, we have a minimization problem. This suggests that the second dual feasible basis is a better one to serve as an initial dual feasible basis. The reason is that in blocks $n-2$, and $n-1$ the coefficients of the variables are larger, and since it is a minimization problem we may expect that we are closer to the optimal basis than in case of the first dual feasible basis.

Numerical Example. Let $n = 6$, and assume that

$$\begin{aligned} p_1 &= 0.30 & p_2 &= 0.35 & p_3 &= 0.55 & p_4 &= 0.40 & p_5 &= 0.30 & p_6 &= 0.35 \\ p_{12} &= 0.15 & p_{13} &= 0.25 & p_{14} &= 0.05 & p_{15} &= 0.15 & p_{16} &= 0.15 \\ p_{23} &= 0.25 & p_{24} &= 0.15 & p_{25} &= 0.15 & p_{26} &= 0.05 \\ p_{34} &= 0.25 & p_{35} &= 0.25 & p_{36} &= 0.25 \\ p_{45} &= 0.15 & p_{46} &= 0.15 \\ p_{56} &= 0.15 \end{aligned}$$

We used the dual method to solve the minimization problem (6). As initial dual feasible basis we chose the collection of vectors in blocks $n-2 = 4$ and $n-1 = 5$.

These vectors have indices 42, ..., 62. After twenty iterations an optimal basis was found, the indices of which are:

12, 13, 16, 20, 22, 25, 28, 29, 36, 38, 39, 43, 44, 45, 48, 50, 51, 52, 54, 55, 56.

The basic components of the primal optimal solution are:

$x_{12} = 0.01$, $x_{13} = 0.02$, $x_{16} = 0.10$, $x_{20} = 0.03$, $x_{22} = 0.08$, $x_{25} = 0.01$, $x_{28} = 0.03$,
 $x_{29} = 0.03$, $x_{36} = 0.05$, $x_{38} = 0.02$, $x_{39} = 0.05$, $x_{43} = 0.02$, $x_{44} = 0.03$, $x_{45} = 0.01$,
 $x_{48} = 0.01$, $x_{50} = 0.08$, $x_{51} = 0.00$, $x_{52} = 0.06$, $x_{54} = 0.05$, $x_{55} = 0.01$, $x_{56} = 0.01$.

The components of the dual optimal dual solution are:

$y_1 = 0.4$, $y_2 = 0.6$, $y_3 = 0.6$, $y_4 = 0.8$, $y_5 = -0.2$, $y_6 = 0.0$,
 $y_{12} = -0.2$, $y_{13} = -0.2$, $y_{14} = -0.4$, $y_{15} = 0.2$, $y_{16} = -0.2$,
 $y_{23} = -0.2$, $y_{24} = -0.4$, $y_{25} = 0.0$, $y_{26} = -0.2$,
 $y_{34} = -0.4$, $y_{35} = 0.0$, $y_{36} = -0.2$,
 $y_{45} = 0.2$, $y_{46} = -0.4$,
 $y_{56} = 0.0$.

The optimum value equals 0.71. The optimum value corresponding to the aggregated problem is 0.70.

We generated the right-hand side vector p in problem (6) in such a way that we defined $x^0 = (x_j^0, j = 1, \dots, 63)^T$, where x_j^0 is different from zero only if $j = 4k$, $k = 1, \dots, 15$, and for these j values we made the assignments $x_j^0 = 0.05$; then we set $p = Ax^0$. In this case $\sum_{j=1}^{63} x_j^0 = 0.75$ and $x_0^0 = 0.25$.

The optimum value of the maximization problem (6) is 1.

3 A Method of Partial Disaggregation to Generate Bounds

Let E_1, \dots, E_s be pairwise disjoint nonempty subsets of the set $\{1, \dots, n\}$ exhausting the set $\{1, \dots, n\}$, and introduce the notation $n_j = |E_j|$, $j = 1, \dots, s$.

Out of the events A_1, \dots, A_n we create s event sequences, where the i^{th} one is $\{A_i, i \in E_j, 1 \leq j \leq s\}$. Any of the events A_1, \dots, A_n is contained in one and only one event sequence. For these event sequences we will use the alternative notations:

$$\begin{aligned} &A_{11}, \dots, A_{1n_1} \\ &\dots \end{aligned} \tag{15}$$

$$A_{s1}, \dots, A_{sn_s}.$$

Let ξ_j designate the number of those events in the j^{th} sequence, which occur, and

$$S_{\alpha_1 \dots \alpha_s} = E \left[\binom{\xi_1}{\alpha_1} \dots \binom{\xi_s}{\alpha_s} \right] \tag{16}$$

$$0 \leq \alpha_j \leq n_j, \quad j = 1, \dots, s.$$

We formulate the multivariate binomial moment problem (see Prékopa (1992, 1993)):

$$\begin{aligned} & \min(\max) \sum_{i_1=0}^{n_1} \dots \sum_{i_s=0}^{n_s} f_{i_1 \dots i_s} x_{i_1 \dots i_s} \\ & \text{subject to} \tag{17} \\ & \sum_{i_1=0}^{n_1} \dots \sum_{i_s=0}^{n_s} \binom{i_1}{\alpha_1} \dots \binom{i_s}{\alpha_s} x_{i_1 \dots i_s} = S_{\alpha_1 \dots \alpha_s} \\ & \alpha_j \geq 0, \quad j = 1, \dots, s, \quad \alpha_1 + \dots + \alpha_s \leq m \\ & \forall i_1, \dots, i_s : x_{i_1 \dots i_s} \geq 0. \end{aligned}$$

The $S_{\alpha_1 \dots \alpha_s}$ ($\alpha_1 + \dots + \alpha_s \leq m$) multivariate binomial moments can be computed from the probabilities $p_{i_1 \dots i_k}$ ($1 \leq i_1 < \dots < i_k \leq m$). In order to simplify the rule how to do this, assume that $E_1 = \{1, \dots, n_1\}, \dots, E_s = \{n_1 + \dots + n_{s-1} + 1, \dots, n_1 + \dots + n_s\}$. Then, we have the equality

$$S_{\alpha_1 \dots \alpha_s} = \sum p_{i_{11} \dots i_{1\alpha_1} \dots i_{s1} \dots i_{s\alpha_s}},$$

where the summation is extended over those indices which satisfy the relations

$$1 \leq i_{11} < \dots < i_{1\alpha_1} \leq n_1$$

...

$$n_1 + \dots + n_{s-1} + 1 \leq i_{s1} < \dots < i_{s\alpha_s} \leq n_1 + \dots + n_s.$$

For example, if $n = 6$ and $E_1 = \{1, 2, 3\}$, $E_2 = \{4, 5, 6\}$, then

$$S_{10} = p_1 + p_2 + p_3, \quad S_{01} = p_4 + p_5 + p_6, \quad S_{20} = p_{12} + p_{13} + p_{23}, \quad S_{02} = p_{45} + p_{46} + p_{56},$$

$$S_{11} = p_{14} + p_{15} + p_{16} + p_{24} + p_{25} + p_{26} + p_{34} + p_{35} + p_{36},$$

$$S_{21} = p_{124} + p_{125} + p_{126} + p_{134} + p_{135} + p_{136} + p_{234} + p_{235} + p_{236},$$

$$S_{22} = p_{1245} + p_{1246} + p_{1256} + p_{1345} + p_{1346} + p_{1356} + p_{2345} + p_{2346} + p_{2356}$$

etc.

We have yet to formulate suitable objective functions for problems (16). These depend on the type of bounds we want to create. Suppose that we want to create bounds for two types of logical functions of events:

- (i) at least r out of A_1, \dots, A_n occur, where $r \geq 1$;
- (ii) exactly r out of A_1, \dots, A_n occur, where $0 \leq r \leq n$.

Then, we formulate the objective functions as follows. In case of (i):

$$f_{i_1 \dots i_s} = 1, \text{ if } i_1 + \dots + i_s \geq r \quad (18)$$

$$f_{i_1 \dots i_s} = 0, \text{ if } i_1 + \dots + i_s < r,$$

and in case of (ii):

$$f_{i_1 \dots i_s} = 1, \text{ if } i_1 + \dots + i_s = r \quad (19)$$

$$f_{i_1 \dots i_s} = 0, \text{ if } i_1 + \dots + i_s \neq r.$$

Problems (16) reduce to problems (2), if $s = 1$, and to problems (7), if $s = n$. Problems (16) are disaggregated counterparts of problems (2), and aggregated counterparts of problems (7). The objective functions (17), and (18) are counterparts of the objective functions (4), (5), and (12), (13), respectively.

Let us introduce the notations:

$P_{(r)}$ = probability that at least r out of A_1, \dots, A_n occur;

$P_{[r]}$ = probability that exactly r out of A_1, \dots, A_n occur.

Further notations are presented in the following tableau:

optimum value	Type, and problem	Objective function
$L_{(r)}$	min, (7)	(12)
$U_{(r)}$	max, (7)	(12)
$L_{[r]}$	min, (7)	(13)
$U_{[r]}$	max, (7)	(13)
$l_{(r)}$	min, (16)	(17)
$u_{(r)}$	max, (16)	(17)
$l_{[r]}$	min, (16)	(18)
$u_{[r]}$	max, (16)	(18)

By construction, we have the following inequalities:

$$l_{(r)} \leq L_{(r)} \leq P_{(r)} \leq U_{(r)} \leq u_{(r)} \quad (20)$$

$$l_{[r]} \leq L_{[r]} \leq P_{[r]} \leq U_{[r]} \leq u_{[r]}. \tag{21}$$

In fact, the problems with optimum values $l_{(r)}$, and $u_{(r)}$ ($l_{[r]}$, and $u_{[r]}$) are aggregations of problems with optimum values $L_{(r)}$, and $U_{(r)}$ ($L_{[r]}$, and $U_{[r]}$), respectively.

The duals of problems (16) are the following:

$$\begin{aligned} & \max(\min) \quad \sum_{\substack{\alpha_j \geq 0, j = 1, \dots, s \\ 1 \leq \alpha_1 + \dots + \alpha_s \leq m}} y_{\alpha_1 \dots \alpha_s} S_{\alpha_1 \dots \alpha_s} \\ & \text{subject to} \tag{22} \\ & \sum_{\substack{\alpha_j \geq 0, j = 1, \dots, s \\ 1 \leq \alpha_1 + \dots + \alpha_s \leq m}} y_{\alpha_1 \dots \alpha_s} \binom{i_1}{\alpha_1} \dots \binom{i_s}{\alpha_s} \leq (\geq) f_{i_1 \dots i_s} \\ & \quad 0 \leq i_j \leq n_j, j = 1, \dots, s \\ & \quad i_1 + \dots + i_s \geq 1. \end{aligned}$$

In the left-hand sides of the constraints of problems (21) there are values of a polynomial of the variables i_1, \dots, i_s , defined on the lattice points of the set $\times_{j=1}^s [0, n_j]$. Replacing z_j for i_j , the m -degree polynomial takes the form

$$P(z_1, \dots, z_s) = \sum_{\substack{\alpha_j \geq 0, j = 1, \dots, s \\ \alpha_1 + \dots + \alpha_s \leq m}} y_{\alpha_1 \dots \alpha_s} \binom{z_1}{\alpha_1} \dots \binom{z_s}{\alpha_s}. \tag{23}$$

Problems (16) provide us with a method to construct polynomials $P(z_1, \dots, z_s)$ for one sided approximation of the function $f_{z_1 \dots z_s}$ which we will also designate by $f(z_1, \dots, z_s)$. Any polynomial can be used to create bound, provided that it runs entirely below or above the function $f(z_1, \dots, z_s)$.

If this latter condition holds, then the bound can be obtained in such a way that we write up the polynomial in the form of (22), subdivide the set $\{1, \dots, n\}$ into pairwise disjoint, nonempty subsets E_1, \dots, E_s , define the $S_{\alpha_1 \dots \alpha_s}$ accordingly, and then make the following assignment: the constant term, if different from zero, is assigned to $S_{0 \dots 0} = 1$ in problem (16), $y_{\alpha_1 \dots \alpha_s}$ is assigned to $S_{\alpha_1 \dots \alpha_s}$ in problem (16) for every $\alpha_1, \dots, \alpha_s$ for which $\alpha_j \geq 0, j = 1, \dots, s, \alpha_1 + \dots + \alpha_s \leq m$. Then, we form the products of the assigned quantities and the $S_{\alpha_1 \dots \alpha_s}$; the sum of the products is the bound.

4 Construction of Polynomials for One-Sided Approximations

In this section we describe a general method to construct polynomials of the type (22) which satisfy (21).

The method consists of construction of dual feasible bases to problem (16). Each dual feasible basis of problem (16) determines a dual vector satisfying the inequalities (21), hence it determines a polynomial (22), which approximates the function f in a one-sided manner.

First we make a general remark. Suppose that the matrix A of the linear programming problem: $\min c^T x$, subject to $Ax = b$, $x \geq 0$, has rank equal to its number of rows m . Let T be an $m \times m$ non-singular matrix and formulate the problem: $\min c^T x$, subject to $(TA)x = Tb$, $x \geq 0$. Then a basis is primal (dual) feasible in one of these two problems if and only if it is primal (dual) feasible in the other one. In fact, if $A = (a_1, \dots, a_n)$, then we have the relations

$$(TB)^{-1}Tb = B^{-1}b$$

$$c_k - c_B^T(TB)^{-1}Ta_k = c_k - c_B^TB^{-1}a_k,$$

which imply the assertion.

Let us associate with problem (16) a multivariate power moment problem in such a way that we replace $i_1^{\alpha_1}, \dots, i_s^{\alpha_s}$ for $\binom{i_1}{\alpha_1} \dots \binom{i_s}{\alpha_s}$ and the power moment $\mu_{\alpha_1 \dots \alpha_s}$ for the binomial moment $S_{\alpha_1 \dots \alpha_s}$ on the right-hand side. A single linear transformation takes the column vector in (16):

$$\left(\binom{i_1}{\alpha_1} \dots \binom{i_s}{\alpha_s} : \alpha_j \geq 0, j = 1, \dots, s; \alpha_1 + \dots + \alpha_s \leq m \right)$$

, into the vector

$$(i_1^{\alpha_1} \dots i_s^{\alpha_s} : \alpha_j \geq 0, j = 1, \dots, s; \alpha_1 + \dots + \alpha_s \leq m)$$

The same transformation applies to the right-hand sides. The matrix of this transformation is non-singular (it is also triangular). Thus, the above remark applies, and therefore a basis in the multivariate binomial moment problem is primal (dual) feasible if and only if the corresponding basis in the multivariate power moment problem is primal (dual) feasible.

In case of the univariate discrete moment problems we have full characterization for the dual feasible bases (see Prékopa (1990b)). In the multivariate case full characterization theorems have not been obtained so far. Some results are presented in Prékopa (1993). We recall a few facts from that paper.

Let us associate the lattice point $(i_1, \dots, i_s) \in R^s$ with the vector

$$\left(\left(\begin{matrix} i_1 \\ \alpha_1 \end{matrix} \right) \dots \left(\begin{matrix} i_s \\ \alpha_s \end{matrix} \right) : \alpha_j \geq 0, j = 1, \dots, s; \alpha_1 + \dots + \alpha_s \leq m \right)$$

of the matrix of the equality constraints of problem (16). Let B_Δ and B^Δ designate the sets of vectors corresponding to the sets of lattice points

$$\{(i_1, \dots, i_s) \mid i_j \geq 0, j = 1, \dots, s; i_1 + \dots + i_s \leq m\}, \tag{24}$$

and

$$\{(n_1 - i_1, \dots, n_s - i_s) \mid i_j \geq 0, j = 1, \dots, s; i_1 + \dots + i_s \leq m\}, \tag{25}$$

respectively. In (23), and (24) we assume that $m \leq n_j, j = 1, \dots, s$. Then both B_Δ and B^Δ are bases in problem (16). The following theorem summarises the results in Theorems 5.1 and 5.2 of Prékopa (1993).

Theorem 4.1 *The bases B_Δ and B^Δ are dual feasible bases in the following types of problems (16):*

Case 1: all divided differences of f of total order $m + 1$ are nonnegative

	<i>m + 1 even</i>	<i>m + 1 odd</i>
B_Δ	<i>min</i>	<i>min</i>
B^Δ	<i>min</i>	<i>max.</i>

Case 2: all divided differences of f of total order $m + 1$ are nonpositive

	<i>m + 1 even</i>	<i>m + 1 odd</i>
B_Δ	<i>max</i>	<i>max</i>
B^Δ	<i>max</i>	<i>min.</i>

□

Any dual feasible basis produces a one-sided approximation for f , hence also a bound. A dual feasible basis in a maximization (minimization) problem produces an upper (lower) bound. If a bound of this type is not satisfactory (e.g. a lower

bound may be negative, an upper bound may be greater than 1, or a lower (upper) bound is not close enough to a known upper (lower) bound), then we regard the basis as an initial dual feasible basis, and carry out the solution of the problem by the dual method. This way we obtain the best possible bound, at least for a given subdivision E_1, \dots, E_s of the set $\{1, \dots, n\}$.

Note that problem (7) has $1 + n + \binom{n}{2} + \dots + \binom{n}{m}$ equality constraints and 2^n variables, whereas problem (16) has $\binom{s+m}{m}$ constraints and $(n_1 + 1) \dots (n_s + 1)$ variables. Thus, problem (16) has a much smaller size than problem (7). For example, if $n = 20$, $s = 2$, $n_1 = n_2 = 10$, $m = 3$, then problem (7) has sizes 1351 and 1,048,576, whereas problem (16) has sizes 10 and 121.

To obtain the best possible bound which can be given by our method, one has to maximize (minimize) the lower (upper) bound with respect to all subdivisions E_1, \dots, E_s of the set $\{1, \dots, n\}$. In practice we use only a few trial subdivisions, and choose that one which provides us with the best bound.

Next, we consider the objective function (17) for the cases of $r = 1$ and $r = n$. If $r = n$, then the function (17) is the same as the function (18). Thus, if $r = 1$, then we look at

$$f_{i_1, \dots, i_s} = \begin{cases} 0 & \text{if } (i_1, \dots, i_s) = (0, \dots, 0) \\ 1 & \text{otherwise,} \end{cases} \quad (26)$$

and if $r = n$, then we look at

$$f_{i_1, \dots, i_s} = \begin{cases} 1 & \text{if } (i_1, \dots, i_s) = (n_1, \dots, n_s) \\ 0 & \text{otherwise.} \end{cases} \quad (27)$$

It is easy to check that all divided differences of any order of the function (26) are nonnegative, and if $m + 1$ is even (odd), then all divided differences of the function (25) of total order $m + 1$ are nonpositive (nonnegative). Combining this with Theorem 4.1, we obtain

Theorem 4.2 *The bases B_Δ and B^Δ are dual feasible bases in the following types of problems (16):*

the objective function is given by (25)

$$\begin{array}{rcc}
 & m + 1 \text{ even} & m + 1 \text{ odd} \\
 B_{\Delta} & \max & \min \\
 B^{\Delta} & \max & \max,
 \end{array}$$

the objective function is given by (26)

$$\begin{array}{rcc}
 & m + 1 \text{ even} & m + 1 \text{ odd} \\
 B_{\Delta} & \min & \min \\
 B^{\Delta} & \min & \max.
 \end{array}$$

□

Note that the problems with objective functions (25), and (26) can be transformed into each other. The optimum value of the problem with objective function (25) is equal to 1-(optimum value of the problem with objective function (26), and $S_{\alpha_1 \dots \alpha_s}$ replaced by $\bar{S}_{\alpha_1 \dots \alpha_s}$). The binomial moments $\bar{S}_{\alpha_1 \dots \alpha_s}$ correspond to the complementary events $\bar{A}_1, \dots, \bar{A}_n$ in the same way as $S_{\alpha_1 \dots \alpha_s}$ correspond to A_1, \dots, A_n .

The polynomials determined by the bases B_{Δ} , and B^{Δ} can be taken from Prékopa (1993). They are multivariate Lagrange interpolation polynomials with base points (23) and (24), respectively. We designate them by $L_{\Delta}(z_1, \dots, z_s)$, and $L^{\Delta}(z_1, \dots, z_s)$, respectively, and present them here in Newton's form:

$$\begin{aligned}
 L_{\Delta}(z_1, \dots, z_s) = & \\
 & \sum_{\substack{i_1 + \dots + i_s \leq m \\ 0 \leq i_j \leq n_j, j = 1, \dots, s}} [0, \dots, i_1; \dots; 0, \dots, i_s; f] \prod_{j=1}^s \prod_{h=0}^{i_j-1} (z_j - h)
 \end{aligned} \tag{28}$$

and

$$\begin{aligned}
 L^{\Delta}(z_1, \dots, z_s) = & \\
 & \sum_{\substack{i_1 + \dots + i_s \leq m \\ 0 \leq i_j \leq n_j, j = 1, \dots, s}} [n_1 - i_1, \dots, n_1; \dots; n_s - i_s, \dots, n_s; f] \prod_{j=1}^s \prod_{h=n_j-i_j+1}^{n_j-1} (z_j - h).
 \end{aligned} \tag{29}$$

In case of function (25) we have $L^{\Delta}(z_1, \dots, z_s) \equiv 1$, and

$$L_{\Delta}(z_1, \dots, z_s) = \sum_{1 \leq i_1 + \dots + i_s \leq m} (-1)^{i_1 + \dots + i_s - 1} \binom{z_1}{i_1} \dots \binom{z_s}{i_s}. \tag{30}$$

In case of function (26) we have $L_\Delta(z_1, \dots, z_s) \equiv 0$, and

$$1 + \sum_{\substack{1 \leq i_1 + \dots + i_s \leq m \\ 0 \leq i_j \leq n_j, j = 1, \dots, s}} L^\Delta(z_1, \dots, z_s) = (-1)^{i_1 + \dots + i_s} \binom{n_1 - z_1}{i_1} \dots \binom{n_s - z_s}{i_s}. \quad (31)$$

Theorem 4.2 tells us the following. If f is the function (25) and $L_\Delta(z_1, \dots, z_s)$ is the polynomial (29), then

$$L_\Delta(z_1, \dots, z_s) \geq (\leq) f(z_1, \dots, z_s), \quad (32)$$

if $m + 1$ is even (odd); if $L^\Delta(z_1, \dots, z_s)$ is the polynomial (30), then

$$L^\Delta(z_1, \dots, z_s) \geq f(z_1, \dots, z_s), \quad (33)$$

no matter if $m + 1$ is even, or odd. If f is the function (26), then we have the inequalities

$$L_\Delta(z_1, \dots, z_s) \leq f(z_1, \dots, z_s), \quad (34)$$

no matter if $m + 1$ is even, or odd, and

$$L^\Delta(z_1, \dots, z_s) \leq (\geq) f(z_1, \dots, z_s), \quad (35)$$

if $m + 1$ is even (odd).

5 Numerical Examples

Example 1. Let $n = 20$, $n_1 = n_2 = 10$, $m = 3$, and assume that we have obtained the following numbers:

$$S_{01} = S_{10} = 4.5, \quad S_{02} = S_{20} = 12, \quad S_{11} = 20.25, \quad S_{03} = S_{30} = 21, \quad S_{12} = S_{21} = 54.$$

The polynomial (29) takes the form

$$L_\Delta(z_1, z_2) \equiv z_1 - \binom{z_1}{2} + \binom{z_1}{3} + z_2 - z_1 z_2 + \binom{z_1}{2} z_2 - \binom{z_2}{2} + z_1 \binom{z_2}{2} + \binom{z_2}{3}, \quad (36)$$

hence the dual vector corresponding to the basis B_Δ equals:

$$y = (0 \ 1 \ -1 \ 1 \ 1 \ -1 \ 1 \ -1 \ 1 \ 1)^T. \quad (37)$$

The polynomial (30) takes the form

$$L^\Delta(z_1, z_2) \equiv 1, \quad (38)$$

hence the dual vector corresponding to the basis B^Δ equals:

$$y = (1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0)^T. \quad (39)$$

Note that B_Δ , and B^Δ correspond to the lattice points $\{(0, 0), (0, 1), (0, 2), (0, 3), (1, 0), (1, 1), (1, 2), (2, 0), (2, 1), (3, 0)\}$, and $\{(10, 7), (10, 8), (10, 9), (10, 10), (9, 8), (9, 9), (9, 10), (8, 9), (8, 10), (7, 10)\}$, respectively.

By (32) we have that $L^\Delta(z_1, z_2) \geq f(z_1, z_2)$, which is a trivial inequality in view of (37). Since $m + 1 = 4$ is even, by (31) we have that $L_\Delta(z_1, z_2) \geq f(z_1, z_2)$ for all (z_1, z_2) . Thus, both B^Δ , and B_Δ are dual feasible bases in the maximization problem (16).

The dual vector (36) produces the trivial upper bound $y^T S = 114.75$, where

$$S = (S_{00}, S_{10}, S_{20}, S_{30}, S_{01}, S_{11}, S_{21}, S_{02}, S_{12}, S_{03})^T.$$

The dual vector (38) produces the upper bound $y^T S = 1$, which is at the same time the optimum value of the maximization problem (16), and the sharp upper bound for $P(\cup_{i=1}^{20} A_i)$.

The sharp lower bound is obtained by the solution of the minimization problem (16). We have used the dual method with initial dual feasible basis B_Δ and obtained the following optimal solution:

$$x_{00} = 0.11, \quad x_{90} = 0.055556, \quad x_{72} = 0.160714, \quad x_{73} = 0, \quad x_{55} = 0.33,$$

$$x_{36} = 0.208333, \quad x_{28} = 0, \quad x_{09} = 0.075397, \quad x_{10,9} = 0, \quad x_{10,10} = 0.06.$$

This provides us with the lower bound:

$$P(\cup_{i=1}^{20} A_i) \geq 1 - x_{00} = 0.89.$$

The dual vector corresponding to the optimal basis is:

$$y = (0, 0.28, -0.0577, 0.0066, 0.2, -0.04, 0.0044, -0.0222, 0.0022, 0).$$

This determines the polynomial

$$L_{\Delta}(z_1, z_2) = 0.28z_1 - 0.0577 \binom{z_1}{2} + 0.0066 \binom{z_1}{3} + 0.2z_2 - 0.04z_1z_2 + \\ 0.0044 \binom{z_1}{2} z_2 - 0.0222 \binom{z_2}{2} + 0.0022z_1 \binom{z_2}{2},$$

which satisfies $L(z_1, z_2) \leq f(z_1, z_2)$ for all (z_1, z_2) .

Example 2. In this example we consider 40 events for which all binomial moments of order up to 11 have been computed. The 40 events have been subdivided into two 20-element groups and all bivariate binomial moments of total order at most 6 have been computed.

Lower and upper bounds for the probability that at least one out of the 40 events occurs have been computed based on the two sets of data. The bounds are displayed for all lower order binomial moments, too. Thus, we have two sequences of bounds. The bounds in the first sequence are optimum values of problems (2), where the objective function is (4) and $r = 1$. The bounds in the second sequence are optimum values of problems (16), where the objective function is (17) and $r = 1$. The latter problem is a partially disaggregated problem, as compared to problem (2).

The results show that much better bounds can be obtained in the latter case. The bounds obtained from the partially disaggregated problem for $m = 6$ are better than those obtained from the aggregated problem for $m = 11$. The data and the bounds are presented below.

Univariate binomial moments, 40 events

S_0	1.000
S_1	8.164
S_2	54.025
S_3	290.574
S_4	1435.025
S_5	7115.369
S_6	34884.230
S_7	158338.877
S_8	637735.541
S_9	2249527.156
S_{10}	6955762.090
S_{11}	18955303.836

**Bivariate binomial moments when the 40 events are subdivided into two
20-element groups**

first group	second group						
	0	1	2	3	4	5	6
0	1.00	1.93	4.70	12.19	41.05	127.37	317.72
1	6.23	3.28	31.15	186.89	794.26	2541.64	
2	46.04	31.15	295.90	1775.41	7545.49		
3	216.09	186.89	1775.41	10652.46			
4	724.30	794.26	7545.49				
5	1848.66	2541.64					
6	3739.79						

Bounds based on univariate binomial moments

m	lower bound	upper bound
1	0.20410	1.00000
2	0.57400	1.00000
3	0.63452	1.00000
4	0.67613	1.00000
5	0.77875	1.00000
6	0.78559	0.97028
7	0.79960	0.92088
8	0.80000	0.81438
9	0.80156	0.81185
10	0.80191	0.80671
11	0.80299	0.80638

Bounds based on bivariate binomial moments

m	lower bound	upper bound
1	0.31137	1.00000
2	0.66045	1.00000
3	0.79552	0.91272
4	0.80255	0.83071
5	0.80275	0.80583
6	0.80325	0.80410

Example 3. In this example we consider 40 events (different from those of Example 2) which we subdivide into two 20-element groups. We have computed the

Bounds based on univariate binomial moments

m	lower bound	upper bound
1	0.09360	1.00000
2	0.13693	0.99709
3	0.43143	0.86736
4	0.63421	0.84467
5	0.66969	0.84276
6	0.75414	0.84128
7	0.76038	0.84127
8	0.77968	0.84126
9	0.78129	0.84120
10	0.78748	0.83873
11	0.78845	0.83831
12	0.78885	0.83824
13	0.78899	0.83042

Bounds based on bivariate binomial moments

m	lower bound	upper bound
1	0.09360	1.00000
2	0.13693	0.96005
3	0.49703	0.85782
4	0.67984	0.84248
5	0.70577	0.84164
6	0.77074	0.84118
7	0.81049	0.83394
8	0.2896	

6 Conclusions

In order to create lower and upper bounds for Boolean functions of events, arranged in a finite sequence, a simple and frequently efficient method is the one provided by the discrete binomial moment problems. These are LP's, where the right-hand side numbers are some of the binomial moments S_1, S_2, \dots . Since S_k is the sum of joint probabilities of k -tuples of events, these LP's are called aggregated problems. Better bounds can be obtained if we use the individual probabilities in the sums of all S_k binomial moments that turn up in the aggregated problem. However, the LP's based on these, called the disaggregated problems, have huge sizes, in general, and we may not be able to solve them. In the present paper we have shown that a third type of problem, which can be placed in between the aggregated and disaggregated problem, can combine solvability and very good bounding performance, at least in many cases. This third problem arises in such a way that we subdivide our event sequence into subsequences and then formulate multivariate discrete moment problems to obtain bounds. Numerical examples show that this new approach is efficient.

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