

**MATH 354:03 LINEAR OPTIMIZATION, SPRING 2012**  
**HANDOUT #2**

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**How to convert an LP into Canonical Form / Standard Form:**

$$\left\{ \begin{array}{rcll} \min & 2x & -y & +4z \\ \text{s.t.} & -x & +7y & +z \geq 3 \\ & -3x & +5y & \leq 15 \\ & -5x & +2y & +4z = 10 \\ & x & & \leq 0 \\ & & y & \geq 0 \end{array} \right\} \xrightarrow{C.F.} \left\{ \begin{array}{rcll} \max & 2x & +y & -4z_1 +4z_2 \\ \text{s.t.} & -x & -7y & -z_1 +z_2 \leq -3 \\ & 3x & +5y & \leq 15 \\ & 5x & +2y & +4z_1 -4z_2 \leq 10 \\ & -5x & -2y & -4z_1 +4z_2 \leq -10 \\ & x & & \geq 0 \\ & & y & \geq 0 \\ & & & z_1 \geq 0 \\ & & & z_2 \geq 0 \end{array} \right\} \xrightarrow{S.F.} \left\{ \begin{array}{rcll} \max & 2x & +y & -4z_1 +4z_2 \\ \text{s.t.} & -x & -7y & -z_1 +z_2 +s_1 = -3 \\ & 3x & +5y & +s_2 = 15 \\ & 5x & +2y & +4z_1 -4z_2 = 10 \\ & x & & \geq 0 \\ & & y & \geq 0 \\ & & & z_1 \geq 0 \\ & & & z_2 \geq 0 \\ & & & s_1 \geq 0 \\ & & & s_2 \geq 0 \end{array} \right\}$$

What we needed to take care was  $x \leq 0$ ,  $z$  unconstrained (or unrestricted), converting min to max, direction of inequalities. **NOTE THAT we introduced as few variables and constraints as possible** (this will be required in the exam too!).

- $z = z_1 - z_2$  (because  $z$  is unrestricted), therefore  $z_1 \geq 0$ ,  $z_2 \geq 0$ .
- $x = -x$  (because  $x \leq 0$ ), therefore  $x \geq 0$ .

**Geometric solution method:**

$$\begin{array}{llll}
 \max & 3x_1 & +2x_2 & +x_3 \\
 \text{s.t.} & x_1 & +x_2 & +x_3 \leq 5 \\
 & 3x_1 & +2x_2 & \leq 12 \\
 & x_1 & & \geq 0 \\
 & & x_2 & \geq 0 \\
 & & & x_3 \geq 0
 \end{array}$$

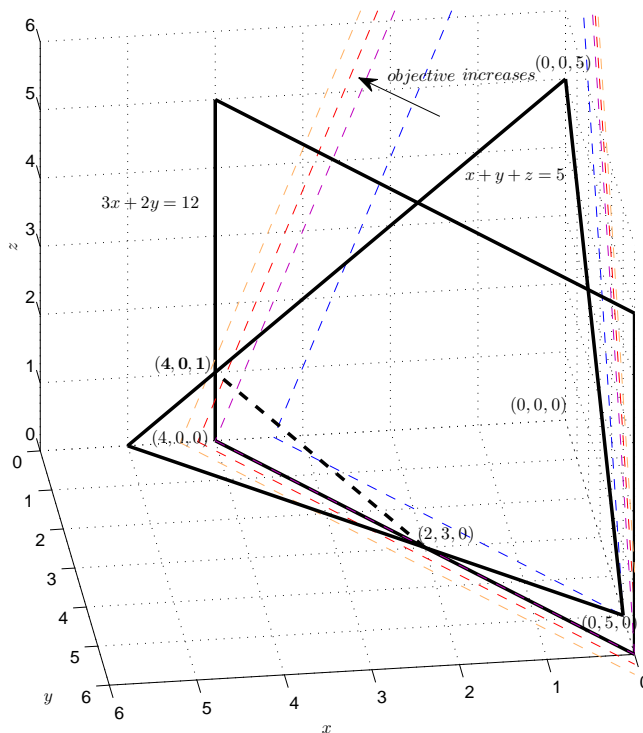


FIGURE 1. Geometrical solution

**WHAT ARE THE BASIC SOLUTIONS TO THIS SYSTEM?**  
all of them, basic feasible and basic infeasible solutions. **WHAT IS A BASIC FEASIBLE SOLUTION!**

**What is simplex table? What does it represent, what are it's entries?**

	$x$	
	$c_B^T B^{-1} A - c$	$c_B^T B^{-1} b$
$x_B$	$B^{-1} A$	$B^{-1} b$

**Proof of homework #2, question #2:**

Let  $\bar{B}$  be the columns of the matrix  $A$  corresponding to the positive components of extreme point  $\bar{x}$  (we assume  $\bar{B}$  is not a basis, hence  $\text{rank}(\bar{B}) = t < m$ ). By rearranging the columns of  $A$  we can rewrite  $A = [\bar{B}, \bar{N}]$  (where  $\bar{N}$  is the rest of the columns from  $A$ ). We apply Gaussian elimination to the columns of  $\bar{B}$ . As the columns of  $\bar{B}$  are linearly independent (we proved in class), we arrive at the following matrix:

$$\bar{A} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 1 \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & 0 \end{bmatrix} N \quad (1)$$

where we have the  $t \times t$  identity matrix on the upper left and  $N$  is the matrix after the Gauss elimination operator applied to matrix  $\bar{N}$ . If the rows  $t + 1$  to  $m$  of  $\bar{A}$  is all-zeros, we derive the contradiction to the rank of matrix  $A$  (as  $\text{rank}(A) = m$ ). Else we select the column of  $\bar{N}$  with at least one non-zero from the rows  $t + 1$  to  $m$  and we can extend  $\bar{B}$  with this column to get a set of columns of rank  $t + 1$ . We iterate until we detect  $\text{rank}(\bar{B}) = m$ .